LaserTurn2 and LaserTurn5

Linear/Rotary Motion Platform

High integration linear/rotary motion platform

Pneumatically actuated 3-jaw gripper or ER collet

Clear aperture for product feedthrough

Optional front and rear tooling platforms

Direct-drive linear and rotary motor technology

Configure for wet or dry cutting

High-speed rotary option for rotational speeds up to 2000 rpm

The LaserTurn[™] series of products are the first dedicated motion subsystems targeted directly at cylindrical laser processing applications. The integrated linear-rotary system combines automated material handling functionality and wet cutting operation with high performance direct-drive linear and rotary motion. The pneumatically actuated 3-jaw gripper has a clear aperture for product feedthrough and can be configured for O.D., I.D., or odd form gripping with various jaw geometries, while the ER collet supports tubing diameters from 0.5 mm to 30 mm.

Integral Tooling Platform

The LaserTurn[™] series can be equipped with front and rear tooling platforms that include tapped holes on four surfaces for various fixture mounting. The tooling platform is bolted directly to the base of the linear stage providing a stiff, common inertial frame of reference. Custom fixtures such as bushing alignment, part collection, or automated material advance assemblies can easily be attached. Metric or English-based hardware and hole patterns are available as are custom configurations with application specific features.

Automated Material Handling

The LaserTurn[™] is a complete motion and material handling subsystem. The system includes an automated, pneumatically activated 3-jaw gripper or ER collet for part holding. The 3-jaw gripper has a clear aperture for product feedthrough and can be configured for O.D., I.D., or odd

form gripping with various jaw geometries. The ER collet chuck also has a clear aperture for product feedthrough and can support tubing diameters from 0.5 mm (0.020 inch) to 30 mm (1.18 inch).

Direct-Drive Technology

The LaserTurn[™] series utilizes direct-drive noncontact motor and encoder technology for both the linear and rotary axes. Direct-drive motors exhibit significantly higher throughput and maintenance-free operation when compared to gear and screw-driven technology. Linear and rotary encoders coupled directly to the load have the highest level of system accuracy and repeatability over the operating lifetime of the stage.

Scalable Product Solutions

Three platforms – the LaserTurn[™]1, LaserTurn[™]2, and the LaserTurn[™]5 – are available to provide support for different price and performance requirements. Each product features the automated material handling capabilities and modular tooling platforms. The LaserTurn[™] 2 has a smaller overall footprint and reduced load carrying capability while providing similar accuracy and repeatability to the larger LaserTurn[™]5.

The LaserTurn[™]5's deeper cross section and larger bearings provide higher throughput and dynamic tracking accuracy for a given load when compared to the LaserTurn[™] 2.

Advanced Control Architecture

The LaserTurn[™] is available with a powerful, yet intuitive Aerotech's advanced control system, with which a user can conveniently optimize the current, velocity, and position servo loops for maximum performance. Advanced

LaserTurn2/LaserTurn5

trajectory generation capabilities such as multi-block look ahead minimize geometry errors in tight profiles by transparently regulating cutting speed. Aerotech's Position Synchronized Laser Firing Output (PSO) functionality automatically adjusts the laser pulse frequency to match the current cutting speed to maintain optimal laser power coupling.



Standard and custom tooling platforms available at the front and rear for simple integration of application specific fixtures. Shown with optional 3 jaw gripper for large diameter or oddform materials.

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LaserTurn2 SPECIFICATIONS

Mechanical Specifications		Linear Axis		Rotary Axis	
Travel	Travel		300 mm	±360 deg. continuous	
	With -E2 Encoder Option	Calibration: ±1 μm Uncalibrated: ±5 μm		170 med (145 med)	
Accuracy	With -E1 Encoder Option	Calibrated: ±1 μm Uncalibrated: ±8 μm	Calibrated: ±1 μm Uncalibrated: ±12 μm	+73 μrad (±15 arc sec)	
Bidirectional Repeatability		±0.	5 µm	±15 µrad (±3 arc sec)	
Straightness		±4 μm	±6 μm	N/A	
Flatness		±4 μm	±6 μm	N/A	
Pitch		39 µrad (8 arc sec)	58 µrad (12 arc sec)	N/A	
Yaw		39 µrad (8 arc sec)	58 µrad (12 arc sec)	N/A	
Maximum Speed ⁽¹⁾		2 m/s		800 rpm 2000 rpm (-HS option)	
Tube Capacity		N/A		10 mm (ER16, Dry Cut) 5.8 mm (ER16, Wet Cut)	
Maximum Force (Continuous)		106.7 N		N/A	
Maximum Torque (Continuou	s)	N/A		2.3 N·m (Dry Cut) 1.6 N·m (Wet Cut)	
	Axial		3.0 kg		
Load Capacity ⁽²⁾	Radial	2.0 kg			
	Moment	3 N·m			
Moving Mass (Unloaded)		10 kg		N/A	
Rotor Inertia (Unloaded)		N/A		0.0006 kg⋅m²	
Stage Mass with Tooling Platforms		26 kg	30 kg	N/A	
Collet Type ⁽³⁾		N/A		ER16	
Collet Runout ⁽⁴⁾		N/A		<25 μm	
Minimum System Air Pressure ⁽⁵⁾		100 psig			
Material		Hardcoated Aluminum Stage Body; Stainless Steel Collet Chuck			
MTBF (Mean Time Between Failure)		10,000 Hours			

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Notes:
1. Maximum speed based on stage capability. Requires selection of appropriate amplifier with sufficient voltage and current.
2. Maximum loads are mutually exclusive. Loading limits are due to the collet chuck mechanism. Contact Aerotech if part load requirements exceed specifications.
3. Collect chuck accepts Rego-fix ER collets manufactured to DIN6499 specifications only.
4. Measured TIR of precision gage pin chucked with an ultra-precision ER collet (DIN6499) 10 mm away from collet face.
5. Collet chuck mechanism is normally-closed. Collet mechanism required air to open collet chuck. Air supply much be dry and oil-less OR 99.99% pure nitrogen. Air or nitrogen must be filtered to 1 microns particle size or better.

Electrical Specifications	
Drive System	Direct-drive servomotor
Feedback System	Non-contact optical encoder, 1 Vpp Sinusoidal output
Maximum Bus Voltage	340 VDC

LaserTurn5 ASR SPECIFICATIONS

Mechanical Specifications		Linear Axis		Rotary Axis
Travel		200 mm	300 mm	±360 deg. continuous
Accuracy	With -E2 Encoder Option	Calibrated: ±1 μm Uncalibrated: ±5 μm		
Accuracy	With -E1 Encoder Option	Calibrated: ±1 μm Uncalibrated: ±8 μm	Calibrated: ±1 μm Uncalibrated: ±12 μm	±73 μrad (±15 arc sec)
Bidirectional Repeatability		±0.	.5 μm	±15 µrad (±3 arc sec)
Straightness		±2 μm	±3 μm	N/A
Flatness		±2 μm	±3 μm	N/A
Pitch		39 µrad (8 arc sec)	49 µrad (10 arc sec)	N/A
Yaw		39 µrad (8 arc sec)	49 µrad (10 arc sec)	N/A
Maximum Speed ⁽¹⁾		2 m/s		800 rpm 2000 rpm (-HS option)
Tube Capacity	Tube Capacity		N/A	
Maximum Force (Continuous)		197.2 N		N/A
Maximum Torque (Continuous)		N/A		2.3 N·m (Dry Cut) 1.6 N·m (Wet Cut)
	Axial	3.0 kg		
Load Capacity ⁽²⁾	Radial	2.0 kg		
	Moment	3 N·m		
Moving Mass (Unloaded)		18 kg		N/A
Rotor Inertia (Unloaded)	Rotor Inertia (Unloaded)		N/A	
Stage Mass with Tooling Platforms		65 kg	69 kg	N/A
Collet Type ⁽³⁾		N/A		ER16
Collet Runout ⁽⁴⁾		N/A		<25 µm
Minimum System Air Pressure ⁽⁵⁾		100 psig		
Material		Hardcoated Aluminum Stage Body; Stainless Steel Collet Chuck		
MTBF (Mean Time Between Failure)		10,000 Hours		

Notes: 1. Maximum speed based on stage capability. Requires selection of appropriate amplifier with sufficient voltage and current. 2. Maximum loads are mutually exclusive. Loading limits are due to the collect chuck mechanism. Contact Aerotech if part load requirements exceed specifications.

Maximum loads are inductantly exclusive. Loading initia are due to the contex interchanism. Contact Aerotech in part load requirements exceed spect 3. Collect chuck accepts Rego-fix ER collets manufactured to DIN6499 specifications only.
 Measured TIR of precision gage pin chucked with an ultra-precision ER collet (DIN6499) 10 mm away from collet face.
 Collet chuck mechanism is normally-closed. Collet mechanism required air to open collet chuck. Air supply much be dry and oil-less OR 99.99% pure nitrogen. Air or nitrogen must be filtered to 1 microns particle size or better.

Electrical Specifications	
Drive System	Direct-drive servomotor
Feedback System	Non-contact optical encoder, 1 Vpp Sinusoidal output
Maximum Bus Voltage	340 VDC

LaserTurn5 ACS Series SPECIFICATIONS

	Mechanical Specifications		Linear Axis		Rotary Axis	
Accuracy With -22 Encoder Option Uncalibrated: ±1 µm Uncalibrated: ±	Travel		200 mm	300 mm	±360 deg. continuous	
With ±1 Encoder Option Calibrated: ±1 µm Uncalibrated:	A	With -E2 Encoder Option			Calibrated ⁽¹⁾ : ±24 µrad (±5 arc sec)	
Straightness $\pm 2 \ \mu m$ $\pm 3 \ \mu m$ N/AFlatness $\pm 2 \ \mu m$ $\pm 3 \ \mu m$ N/APitch $39 \ \mu rad (6 \ arc \ sec)$ $49 \ \mu rad (10 \ arc \ sec)$ N/AYaw $39 \ \mu rad (6 \ arc \ sec)$ $49 \ \mu rad (10 \ arc \ sec)$ N/AMaximum Speed(2) $39 \ \mu rad (6 \ arc \ sec)$ $49 \ \mu rad (10 \ arc \ sec)$ N/ATube Capacity $12 \ m m \ (ER25, Dr \ Cut)$ $0.5-16 \ mm \ (ER25, Dr \ Cut)$ $1-12 \ mm \ (ER25, Dr \ Cut)$ Maximum Force (C-trinuous) $197.2 \ mm \ (ER40)$ N/AN/AMaximum Torque (C-trinuous) $197.2 \ mm \ (ER25), 15 \ mm \ (ER40)$ N/AMaximum Torque (C-trinuous) $Axial$ $10 \ kg \ (ER25), 15 \ kg \ (ER40)$ N/AMoment $6 \ kg \ (ER25), 12 \ kg \ (ER40)$ N/AMoving Mass (Unloarder) $MA \ D.006 \ kg \ m^2$ N/ARotor Inertia (Unloarder) $70 \ kg$ $70 \ kg$ $70 \ kg$ N/A Collet Type(4)Platforms $70 \ kg$ $75 \ kg$ N/A Collet Runout(5)Platforms $70 \ kg$ $75 \ kg$ N/A Inimum System Air Pressure(6) $100 \ psig$ $100 \ psig$	Accuracy	With -E1 Encoder Option			Uncalibrated: ±146 µrad (±30 arc sec)	
$\begin{tabular}{ c c c } \hline Flatness & ± 2 μm & ± 3 μm$ N/A$ \\ \hline ± 2 μm & ± 3 μm$ (10 arc sec) $$ 49 μrad (10 arc sec) $$ N/A \\ \hline 49 μrad (10 arc sec) $$ 49 μrad (10 arc sec) $$ N/A \\ \hline 49 μrad (10 arc sec) $$ 49 μrad (10 arc sec) $$ N/A \\ \hline 49 μrad (10 arc sec) $$ 49 μrad (10 arc sec) $$ N/A \\ \hline 49 μrad (10 arc sec) $$ 100 $$ n/A \\ \hline 49 μrad (10 arc sec) $$ 100 $$ n/A \\ \hline 10 10 $arc sec) $$ 100 $$ n/A \\ \hline 11 12 $mm (ER25, Dr Cut) $$ 11 12 $mm (ER25, Dr Cut) $$ 11 12 $mm (ER25, Vet Cut) $$ 16 30 $mm (ER40) $$ \\ \hline 11 12 $mm (ER25, Vet Cut) $$ 16 30 $mm (ER40) $$ \\ \hline 11 12 $mm (ER25, Vet Cut) $$ 16 30 $mm (ER40) $$ \\ \hline 11 12 $mm (ER25), 15$ $kg (ER40) $$ \\ \hline 10 $kg (ER25), 10$ $kg (ER40) $$ \\ \hline 10 $kg (ER25), 10$ $kg (ER40) $$ \\ \hline 10 $kg (ER25), 10$ $kg (ER40) $$ \\ \hline 10 $kg (ER25), 10$ $kg (ER40) $$ \\ \hline 10 $kg (ER25), 12$ $kg (ER40) $$ \\ \hline 10 $kg (ER25), 12$ $kg (ER40) $$ \\ \hline 10 $kg (ER25), 12$ $kg (ER40) $$ \\ \hline 10 $nonet $$ $$ n/A $$ $$ $$ n/A $$ \\ \hline 10 $nonet $$ $$ $n $$ $$ n/A $$ $$ $$ $$ n/A $$ $$ $$ $$ $$ $$ $$ $$ $$ $$ $$ $$ $$	Bidirectional Repea	tability	±0.5 μ	im	±15 µrad (±3 arc sec)	
Pitch39 µrad (8 arc sec)49 µrad (10 arc sec)N/AYaw39 µrad (8 arc sec)49 µrad (10 arc sec)N/AMaximum Speed(2) $39 µrad (8 arc sec)$ 49 µrad (10 arc sec)N/ATube Capacity $2 m/s$ $300 rpm$ Tube Capacity $1.12 mm (ER25, Dr) Cut)$ $1.12 mm (ER25, Dr) Cut)$ Maximum Force (\subset ti nuous) $197.2 \vee$ N/A Maximum Torque (\subset ti nuous) $197.2 \vee$ N/A Maximum Torque (\subset ti nuous) N/A N/A Maximum Torque (\subset ti nuous) N/A $5.06 N \cdot m$ Maximum Torque (\Box ti nuous) N/A $5 kg (ER25), 10 kg (ER25), 10 kg (ER25), 10 kg (ER25), 12 kg (ER40))$ Moving Mass (Unlezero) $Moment$ $6 kg (ER25), 12 kg (ER40)$ Moving Mass (Unlezero) N/A N/A Rotor Inertia (Unlozero) $70 kg$ $75 kg$ Stage Mass with \Box Platforms $70 kg$ $75 kg$ Collet Type(4) $Ch N/A$ $Ch N/A$ Collet Runout(5) N/A $Cle S_2 \mu m$ Minimum System Air ressure(6) $100 psig$	Straightness		±2 μm	±3 μm	N/A	
Yaw 39 μrad (8 arc sec) 49 μrad (10 arc sec) N/A Maximum Speed ⁽²⁾ 2 m/s 300 rpm Tube Capacity N/A 0.5-16 mm (ER25, Dry Cut) 1-12 mm (ER25, Wet Cut) 16-30 mm (ER40) Maximum Force (Commous) 197.2 N N/A Maximum Torque (Commous) Axial 10 kg (ER25), 15 kg (ER40) Moment 6 kg (ER25), 10 kg (ER40) N/A Moving Mass (Unloated) 0.006 kg m ² N/A Rotor Inertia (Unloated) 70 kg 75 kg N/A Collet Type ⁽⁴⁾ Collet N/A ER25, ER40 <25 µm	Flatness		±2 μm	±3 μm	N/A	
Maximum Speed ⁽²⁾ Z m/s 300 rpm Tube Capacity N/A 0.5-16 mm (ER25, Dry Cut) 1-12 mm (ER25, Wet Cut) 16-30 mm (ER40) Maximum Force (Cortinuous) 197.2 N N/A Maximum Torque (Cortinuous) Axial 100 kg (ER25), 15 kg (ER40) Moving Mass (Unlocud) Moment 6 kg (ER25), 12 kg (ER40) Moving Mass (Unlocud) N/A 0.006 kg·m² Stage Mass with Tooling Platforms 70 kg 75 kg N/A Collet Type ⁽⁴⁾ Collet Nicut (fo) K 25 µm Minimum System Air Pressure ⁽⁶⁾ </td <td>Pitch</td> <th></th> <td>39 µrad (8 arc sec)</td> <td>49 µrad (10 arc sec)</td> <td>N/A</td>	Pitch		39 µrad (8 arc sec)	49 µrad (10 arc sec)	N/A	
Tube Capacity N/A 0.5-16 mm (ER25, Dry Cut) 1-12 mm (ER25, Wet Cut) 16-30 mm (ER40) Maximum Force (C→tinuous) 197.2 N N/A Maximum Torque (→tinuous) N/A 5.06 N·m Moment 6 kg (ER25), 15 kg (ER40) Moving Mass (Unlo→t) N/A 0.006 kg·m² Rotor Inertia (Unlo→t) N/A 0.006 kg·m² Stage Mass with To-ing Platforms 70 kg 75 kg N/A Collet Type ⁽⁴⁾ N/A ER25, ER40 Collet Runout ⁽⁵⁾ N/A <25 µm	Yaw		39 µrad (8 arc sec)	49 µrad (10 arc sec)	N/A	
Tube Capacity N/A 1-12 mm (ER25, Wet Cut) 16-30 mm (ER40) Maximum Force (C→Tinuous) 0 197.2 N N/A Maximum Torque (C→Tinuous) N/A N/A 5.06 N·m Maxia N/A 5.06 N·m 5.06 N·m Maxia N/A 5.06 N·m 5.06 N·m Maxia Maxia 10 kg (ER25), 15 kg (ER40) 5.06 N·m Morent 6 kg (ER25), 10 kg (ER40) N/A Moving Mass (Uniove) 0.006 kg·m² N/A Rotor Inertia (Uniove) N/A 0.006 kg·m² Stage Mass with Torig 70 kg 75 kg N/A Collet Type ⁽⁴⁾ 70 kg 75 kg ER25, ER40 Collet Runout ⁽⁵⁾ N/A ER25, ER40 Minimum System Air (ef) 100 psig 100 psig	Maximum Speed ⁽²⁾		2 m/	S	300 rpm	
Maximum Torque (Votinuous) N/A 5.06 N·m Axial 10 kg (ER25), 15 kg (ER40) Load Capacity ⁽³⁾ Radial 5 kg (ER25), 10 kg (ER40) Moment 6 kg (ER25), 12 kg (ER40) Moving Mass (Unlow N/A Rotor Inertia (Unloaded) N/A Stage Mass with Torpe Platforms 70 kg 75 kg Collet Type ⁽⁴⁾ N/A ER25, ER40 Collet Runout ⁽⁶⁾ N/A 23 kg Minimum System Air Pressure ⁽⁶⁾ N/A 25 μm	Tube Capacity		N/A		1-12 mm (ER25, Wet Cut)	
Axial 10 kg (ER25), 15 kg (ER40) Radial 5 kg (ER25), 10 kg (ER40) Moment 6 kg (ER25), 12 kg (ER40) Moving Mass (Unloaded) 0.006 kg·m² Rotor Inertia (Unloaded) 70 kg 75 kg N/A Stage Mass with Tooling Platforms 70 kg 75 kg N/A Collet Type ⁽⁴⁾ N/A ER25, ER40 Moment N/A ER25, ER40 Mode to the transmet for t	Maximum Force (Co	ontinuous)	197.2 N		N/A	
Load Capacity(3) Radial 5 kg (ER25), 10 kg (ER40) Moment 6 kg (ER25), 12 kg (ER40) Moving Mass (Unloated) 23 kg N/A Rotor Inertia (Unloated) 0.006 kg·m² 0.006 kg·m² Stage Mass with Tooling Platforms 70 kg 75 kg N/A Collet Type ⁽⁴⁾ 0.006 kg·m² 0.006 kg·m² 0.006 kg·m² Collet Runout ⁽⁵⁾ 0.006 kg·m² 0.006 kg·m² 0.006 kg·m² Minimum System Air Pressure ⁽⁶⁾ 0.006 kg·m² 0.006 kg·m² 0.006 kg·m²	Maximum Torque (Continuous)		N/A		5.06 N∙m	
Moment 6 kg (ER25), 12 kg (ER40) Moving Mass (Unloaded) 23 kg N/A Rotor Inertia (Unloaded) N/A 0.006 kg·m² Stage Mass with Tooling Platforms 70 kg 75 kg N/A Collet Type ⁽⁴⁾ N/A ER25, ER40 25 μm Minimum System Air Pressure ⁽⁶⁾ 100 psig 100 psig	Axial		10 kg (ER25), 15 kg (ER40)			
Moving Mass (Unloaded) 23 kg N/A Rotor Inertia (Unloaded) N/A 0.006 kg·m² Stage Mass with Tooling Platforms 70 kg 75 kg N/A Collet Type ⁽⁴⁾ N/A ER25, ER40 25 μm Minimum System Air Pressure ⁽⁶⁾ 100 psig 100 psig	Load Capacity ⁽³⁾	Radial	5 kg (ER25), 10 kg (ER40)			
Rotor Inertia (Unloaded) N/A 0.006 kg·m² Stage Mass with Tooling Platforms 70 kg 75 kg N/A Collet Type ⁽⁴⁾ N/A ER25, ER40 Collet Runout ⁽⁵⁾ N/A <25 μm		Moment	6 kg (ER25), 12 kg (ER40)			
Stage Mass with Tooling Platforms 70 kg 75 kg N/A Collet Type ⁽⁴⁾ N/A ER25, ER40 Collet Runout ⁽⁵⁾ N/A <25 μm	Moving Mass (Unloa	aded)	23 kg		N/A	
Collet Type ⁽⁴⁾ N/A ER25, ER40 Collet Runout ⁽⁵⁾ N/A <25 μm Minimum System Air Pressure ⁽⁶⁾ 100 psig	Rotor Inertia (Unloaded)		N/A		0.006 kg⋅m²	
Collet Runout ⁽⁵⁾ N/A <25 μm Minimum System Air Pressure ⁽⁶⁾ 100 psig 100 psig	Stage Mass with Tooling Platforms		70 kg	75 kg	N/A	
Minimum System Air Pressure ⁽⁶⁾ 100 psig	Collet Type ⁽⁴⁾		N/A		ER25, ER40	
	Collet Runout ⁽⁵⁾		N/A		<25 µm	
Material Hardcoated Aluminum Stage Body; Stainless Steel Collet Chuck	Minimum System Air Pressure ⁽⁶⁾		100 psig			
	Material		Hardcoated Aluminum Stage Body; Stainless Steel Collet Chuck			
MTBF (Mean Time Between Failure) 10,000 Hours	MTBF (Mean Time Between Failure)		10,000 Hours			

Notes:

Notes:
1. Requires Aerotech controller and part programming as a rotary axis.
2. Maximum speed based on stage capability. Requires selection of appropriate amplifier with sufficient voltage and current.
3. Maximum loads are mutually exclusive. Loading limits are due to the collet chuck mechanism. Contact Aerotech if part load requirements exceed specifications.
4. Collect chuck accepts Rego-fix ER collets manufactured to DIN6499 specifications only.
5. Measured TIR of precision gage pin chucked with an ultra-precision ER collet (DIN6499) 10 mm away from collet face.
6. Collet chuck mechanism is normally-closed. Collet mechanism required air to open collet chuck. Air supply much be dry and oil-less OR 99.99% pure nitrogen. Air or nitrogen must be filtered to 1 microns particle size or better.

Electrical Specifications	
Drive System	Direct-drive servomotor
Feedback System	Non-contact optical encoder, 1 Vpp Sinusoidal output
Maximum Bus Voltage	340 VDC





NO TOOLING



55 TOOLING PLATFORM TO WORK POINT

> FRONT TOOLING (-FT1/-FT4) & REAR TOOLING (-RT1/-RT2)



LaserTurn 2 ASR DIMENSIONS



LaserTurn 5 ASR DIMENSIONS





LaserTurn 5 ACS DIMENSIONS



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LaserTurn 5 ACS DIMENSIONS



LaserTurn2 Linear/Rotary Motor Platform ORDERING INFORMATION

Travel (Required) -200	200 mm linear axis travel
300	300 mm linear axis travel
eedback (Required)	
E1	Incremental linear encoder, 1 Vpp (linear axis)
E2	High-accuracy incremental linear encoder, 1 Vpp (linear axis)
Rotary Speed (Required)	
SS	Standard speed rotary axis
HS	High speed rotary axis
Cutting Configuration (Req	uired)
DCUT	Dry cutting configuration
WCUT	Wet cutting configuration with fluid rotary union
Front Tooling (Optional)	
FT1	Metric front tooling platform
FT2	Metric front tooling platform with gripper
FT3	Metric front tooling platform with alignment gripper
FT4	English front tooling platform
FT5	English front tooling platform with gripper
FT6	English front tooling platform with alignment gripper
Gripper Jaws (Optional)	
-J1	Gripper jaws for 0-10 mm tube diameters
Rear Tooling (Optional)	
·RT1	Metric rear tooling platform
·RT2	English rear tooling platform
Metrology - Linear (Requir	
PL1 PL2	Metrology, uncalibrated with performance plots Metrology, calibrated (halar) with performance plots
FL2 Aetrology option applies to linear a	
ntegration (Required)	
following standard integrati	rd and custom integration services to help you get your system fully operational as quickly as possible. The on options are available for this system. Please consult Aerotech if you are unsure what level of integration is stom integration support with your system.
TAS	Integration - Test as system
	Testing, integration, and documentation of a group of components as a complete system that will
	be used together (ex: drive, controller, and stage). This includes parameter file generation, system
TAC	tuning, and documentation of the system configuration. Integration - Test as components
TAC	Testing and integration of individual items as discrete components that ship together. This is
	typically used for spare parts, replacement parts, or items that will not be used together. These
	components may or may not be part of a larger system.
Accessories (to be ordered	as separate line item)
Collet-ER16-CLTxxx	ER16 collet - consult with Aerotech for available sizes
RingSeal-ER16-RSxx	Ring seal for wet cutting - consult with Aerotech for available sizes
CGF	Collet and Gripper Filtration Kit

LaserTurn5-ASR Linear/Rotary Motion Platform ORDERING INFORMATION

200	200 mm linear axis travel
300	300 mm linear axis travel
Feedback (Required)	
·E1	Incremental linear encoder, 1 Vpp (linear axis)
E2	High-accuracy incremental linear encoder, 1 Vpp (linear axis)
Rotary Speed (Required)	
-SS	Standard speed rotary axis
-HS	High speed rotary axis
Cutting Configuration (Required)	
-DCUT	Dry cutting configuration
-WCUT	Wet cutting configuration with fluid rotary union
Front Tooling (Optional)	
-FT1	Metric front tooling platform
-FT2	Metric front tooling platform with gripper
-FT3	Metric front tooling platform with alignment gripper
-FT4	English front tooling platform
-FT5	English front tooling platform with gripper
-FT6	English front tooling platform with alignment gripper
Gripper Jaws (Optional)	
-J1	Gripper jaws for 0-10 mm tube diameters
Rear Tooling (Optional)	
-RT1	Metric rear tooling platform
-RT2	English rear tooling platform
Metrology - Linear (Required)	
-PL1	Metrology, uncalibrated with performance plots
-PL2	Metrology, calibrated (halar) with performance plots
Metrology option applies to linear axis only.	
Integration (Required)	

following standard integration options are available for this system. Please consult Aerotech if you are unsure what level of integration is required, or if you desire custom integration support with your system.

-TAS	Integration - Test as system Testing, integration, and documentation of a group of components as a complete system that will be used together (ex: drive, controller, and stage). This includes parameter file generation, system tuning and documentation of the curter configuration
-TAC	tuning, and documentation of the system configuration. Integration - Test as components
	Testing and integration of individual items as discrete components that ship together. This is typically used for spare parts, replacement parts, or items that will not be used together. These components may or may not be part of a larger system.

Accessories (to be ordered as separate line item)

Collet-ER16-CLTxxx	ER16 collet - consult with Aerotech for available sizes
RingSeal-ER16-RSxx	Ring seal for wet cutting - consult with Aerotech for available sizes
CGF	Collet and Gripper Filtration Kit

LaserTurn 5 ACS Series ORDERING INFORMATION

Travel (Required)	
-200	200 mm linear axis travel
-300	300 mm linear axis travel
Feedback (Required)	
-E1	Incremental linear encoder, 1 Vpp (linear axis)
-E2	High-accuracy incremental linear encoder, 1 Vpp (linear axis)
Collet Style (Required)	
-ER25	ER25 ultra-precision collet chuck
-ER40	ER40 ultra-precision collet chuck
Cutting Configuration (Required)	
-DCUT	Dry cutting configuration
-WCUT	Wet cutting configuration with fluid rotary union
Front Tooling (Optional)	
-FT1	Metric front tooling platform
-FT2	Metric front tooling platform with gripper
-FT3	Metric front tooling platform with alignment gripper
-FT4	English front tooling platform
-FT5	English front tooling platform with gripper
-FT6	English front tooling platform with alignment gripper
Gripper Jaws (Optional)	
-J1	Gripper jaws for 0-10 mm tube diameters
-J2	Gripper jaws for 8-18 mm tube diameters
-J3	Gripper jaws for 16-26 mm tube diameters
-J4	Gripper jaws for 24-34 mm tube diameters
Rear Tooling (Optional)	
-RT1	Metric rear tooling platform
-RT2	English rear tooling platform
Metrology - Linear (Required)	
-PL1	Metrology, uncalibrated with performance plots
-PL2	Metrology, calibrated (halar) with performance plots
Metrology option applies to linear axis only.	
Metrology - Rotary (Required)	
-PL1	Metrology, uncalibrated with performance plots
-PL2	Metrology, calibrated (halar) with performance plots

Metrology option applies to linear axis only

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LaserTurn 5 ACS Series ORDERING INFORMATION

Integration (Required)

Aerotech offers both standard and custom integration services to help you get your system fully operational as quickly as possible. The following standard integration options are available for this system. Please consult Aerotech if you are unsure what level of integration is required, or if you desire custom integration support with your system.

-TAS	Integration - Test as system
	Testing, integration, and documentation of a group of components as a complete system that will
	be used together (ex: drive, controller, and stage). This includes parameter file generation, system
	tuning, and documentation of the system configuration.
-TAC	Integration - Test as components
	Testing and integration of individual items as discrete components that ship together. This is
	typically used for spare parts, replacement parts, or items that will not be used together. These
	components may or may not be part of a larger system.

Accessories (to be ordered as separate line item)