



# ATX115SL and SLE Mechanical-Bearing, Screw-Driven Linear Stage

## HARDWARE MANUAL

Revision 2.00



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## EU Declaration of Incorporation

**Manufacturer** Aerotech, Inc.  
101 Zeta Drive  
Pittsburgh, PA 15238-2811  
USA



herewith declares that the product:

### ATX115SL/SLE stage

is intended to be incorporated into machinery to constitute machinery covered by the Directive 2006/42/EC as amended; and that the following harmonized European standards have been applied:

#### EN ISO 12100:2010

**Safety of Machinery - Basic concepts, general principles for design**

#### EN 60204-1:2010

**Safety of Machinery - Electrical equipment of machines - Part 1: General requirements**

and further more declares that

it is not allowed to put the equipment into service until the machinery into which it is to be incorporated or of which it is to be a component has been found and declared to be in conformity with the provisions of the Directive 2006/42/EC and with national implementing legislation, for example, as a whole, including the equipment referred to in this Declaration.

This is to certify that the aforementioned product is in accordance with the applicable requirements of the following directive(s):

**EU 2015/863**

**Directive, Restricted Substances (RoHS 3)**

**Authorized Representative:**

/ Norbert Ludwig

Managing Director  
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**Engineer Verifying Compliance**

/ Alex Weibel

Aerotech, Inc.  
101 Zeta Drive  
Pittsburgh, PA 15238-2811  
USA  
9/12/2023

**Date**

## UKCA Declaration of Incorporation

**Manufacturer**  
Aerotech, Inc.  
101 Zeta Drive  
Pittsburgh, PA 15238-2811  
USA



herewith declares that the product:

### **ATX115SL/SLE stage**

To which this declaration relates, meets the essential health and safety requirements and is in conformity with the relevant UK Legislation listed below:

### **Supply of Machinery (Safety) Regulations 2008**

### **Hazardous Substances in Electrical and Electronic Equipment Regulations 2012**

Using the relevant section of the following UK Designated Standards and other normative documents when installed in accordance with the installation instructions supplied by the manufacturer.

### **EN ISO 12100:2010**

### **Safety of Machinery - Basic concepts, general principles for design**

### **EN 60204-1:2010**

### **Safety of Machinery - Electrical equipment of machines - Part 1: General requirements**

and furthermore declares that it is not allowed to put the product into service until the machinery into which it is to be incorporated or of which it is to be a component has been found and declared to be in conformity with the provisions of the Supply of Machinery (Safety) Regulations 2008 UK Legislation and with national implementing legislation, for example, as a whole, including the equipment referred to in this Declaration.

**Authorized Representative:**

A handwritten signature in black ink, appearing to read 'Simon Smith'.

/ Simon Smith

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/ Alex Weibel

Aerotech, Inc.  
101 Zeta Drive  
Pittsburgh, PA 15238-2811  
USA

**Date**

9/12/2023

## Safety Procedures and Warnings



**IMPORTANT:** This manual tells you how to carefully and correctly use and operate the stage.

- Read all parts of this manual before you install or operate the stage or before you do maintenance to your system.
- To prevent injury to you and damage to the equipment, obey the precautions in this manual.
- All specifications and illustrations are for reference only and were complete and accurate as of the release of this manual. To find the newest information about this product, refer to [www.aerotech.com](http://www.aerotech.com).

If you do not understand the information in this manual, contact Aerotech Global Technical Support.



**IMPORTANT:** This product has been designed for light industrial manufacturing or laboratory environments. If the product is used in a manner not specified by the manufacturer:

- The protection provided by the equipment could be impaired.
- The life expectancy of the product could be decreased.

Safety notes and symbols are placed throughout this manual to warn you of the potential risks at the moment of the safety note or if you fail to obey the safety note.



Shock/Electrocution Hazard



Pinch, Shear, or Crush Hazard



General/Conditional Awareness



Rotational Machinery Hazard



Hot Surface Hazard



Pinch/Entanglement Hazard



Magnetic Field Hazard



Trip Hazard



Heavy, Bulky Lifting Hazard



Appropriate Equipment Required



Pressure/Explosive Atmosphere Hazard



Electrostatic Discharge Hazard

A blue circle symbol is an action or tip that you should obey. Some examples include:



General tip



Read the manual/section



Wear personal protective equipment (PPE): Safety Glasses



If applicable, do not lift unassisted



Wear personal protective equipment (PPE): Gloves



Wear personal protective equipment (PPE): Hearing Protection

## Installation and Operation

To decrease the risk of damage to the equipment, you must obey the precautions that follow.



### **DANGER: General Hazard Warning!**

This product can produce high forces and move at velocities that could cause injury. The user is responsible for its safe operation. The following general equation is provided to assist with risk assessments in regards to contact and pinch points:

$$Pressure_{Max} \left[ \frac{N}{mm^2} \right] = \frac{Force_{Peak} [N]}{Area_{Contact} [mm^2]}$$



### **WARNING: General Hazard Warning!**

- Only trained operators should operate this equipment.
- All service and maintenance must be done by approved personnel.
- Use this product only in environments and operating conditions that are approved in this manual.
- Never install or operate equipment that appears to be damaged.
- On stages with BMS motors: the motor over-temperature sensor must be monitored by the drive. Use it to shut down the drive if the motor overheats.
- Make sure that the product is securely mounted before you operate it.
- Make sure that all pneumatic lines are securely connected.
- Use care when you move the stage or you could negatively affect the performance of it.



### **WARNING: Trip Hazard!**

Route, house, and secure all cables, duct work, air, or water lines. Failure to do so could introduce trip hazards around the system that could result in physical injury or could damage the equipment.

## Electrical Warnings

To decrease the risk of electrical shock, injury, death, and damage to the equipment, obey the precautions that follow.



### **DANGER: Electrical Shock Hazard!**

- Stage motor phase voltage levels could be hazardous live.
- Personnel are protected from hazardous voltages unless electrical interconnections, protective bonding (safety ground), or motor/stage enclosures are compromised.
- Do not connect or disconnect stage/motor interconnections while connected to a live electrical power source.
- Before you set up or do maintenance, disconnect electrical power.
- It is the responsibility of the End User/System Integrator to make sure that stages are properly connected and grounded per Engineering Standards and applicable safety requirements.
- It is the responsibility of the End User/System Integrator to configure the system drive or controller within the Aerotech motor/stage electrical and mechanical specifications.

## Motor-Related Warnings

Aerotech motors are capable of producing high forces and velocities. Obey all warnings and all applicable codes and standards when you operate a system that incorporates Aerotech motors.

### DANGER: Mechanical Hazard!



Personnel must be made aware of the mechanical hazards during set up or when you do service to the stage.



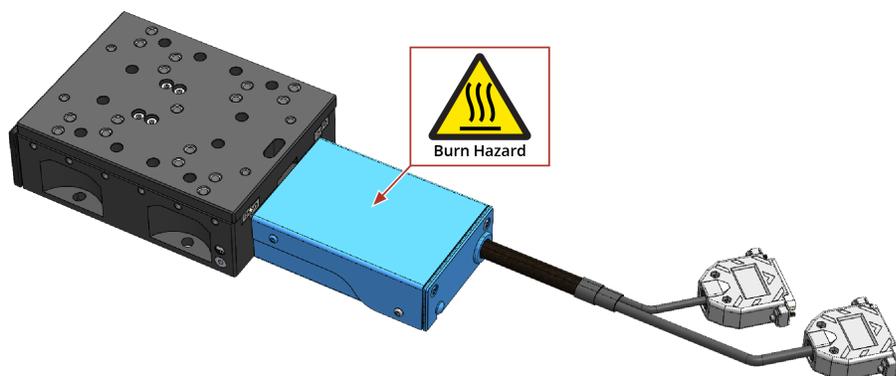
- Unintentional manual movement into the stage "end-of-travel" stops, could damage the stage or undo precision alignments.
- Stage movement could create pinch points, entanglement hazards, or rotational mechanical hazards.

### DANGER: Hot Surface Hazard!



- The stage/motor frame temperature could exceed 70°C in some applications.
- Do not touch the stage/motor frame while it is in operation.
- Wait until the stage/motor has cooled before you touch it.

Figure 1: Motor Location



### DANGER: Risk in Explosive Atmosphere!



- Standard Aerotech stage/motors are not rated for applications with explosive atmospheres such as airborne dust or combustible vapors.
- Do not operate stage/motors outside of Aerotech environmental specifications.

### DANGER: Magnetic Field Hazard!



Aerotech stage/motors contain magnets which can present a Magnetic Field Hazard.

- Do not disassemble a stage motor under any circumstances.
- Strong magnetic fields could interfere with external/internal medical devices.
- Strong magnetic fields could present mechanical hazards such as pinch points.

## Pinch Points

A pinch point is a mechanical hazard that can occur when there are exposed parts of the stage or system that can move. For example, the travel of a stage tabletop could expose the user to a pinch point between the tabletop and the stage housing. The images that follow will show you typical external and internal pinch point locations.

### **DANGER: Mechanical Hazard!**



- System travel can cause crush, shear, or pinch injuries.
- Only trained operators should operate this equipment.
- Do not put yourself in the travel path of machinery.
- Restrict access to all motor and stage parts
  - when the system moves under power (during normal operation, for example).
  - when the system is moved manually (during the installation process or when you do maintenance, for example).
- Motors are capable of very high speeds and acceleration rates.

**Figure 2: Typical Pinch Point Locations**



## Handling and Storage



**IMPORTANT:** It is the responsibility of the customer to safely and carefully lift and move the stage.

- Be careful when you move or transport the stage.
- Retain the shipping materials for future use.
- Transport or store the stage in its protective packaging.



### **WARNING: Electrostatic Discharge (ESD) Sensitive Components!**

Wear an ESD wrist strap when you handle, install, or do service to the system assembly. You could damage the power supply or drives if you fail to observe the correct ESD practices.

Inspect the shipping container for any evidence of shipping damage. If any damage exists, notify the shipping carrier immediately.

Remove the packing list from the shipping container. Make sure that all the items specified on the packing list are contained within the package.

The documentation for the stage is on the included installation device. The documents include manuals, interconnection drawings, and other documentation pertaining to the system. Save this information for future reference.

Each stage has a label listing the system part number and serial number. These numbers contain information necessary for maintenance or system hardware and software updates. Locate this label and record the information for later reference.

## Unpacking and Handling

It is the responsibility of the customer to safely and carefully lift and move the stage.



**IMPORTANT:** All electronic equipment and instrumentation is wrapped in antistatic material and packaged with desiccant. Ensure that the antistatic material is not damaged during unpacking.



**DANGER: Lifting Hazard!** Use care when you move the stage or you could negatively affect the performance of it.

- Use the correct lifting techniques, mechanical assistance, or additional help to lift or move this product.
- Do not use the cables or the connectors to lift or move this product.
- Make sure that all moving parts are secure before you move the stage. Unsecured moving parts could shift and cause injury or damage to the equipment.
- If the stage is heavy, a single person lift could cause injury. Use assistance when you lift or move it.
  - Refer to [Section 2.1. Dimensions](#) for dimensions
  - Refer to [Section 1.3. Basic Specifications](#) for weight specifications.

Carefully remove the stage from its protective shipping container.

- Lift this product only by the base.
- Use lifting hardware if it has been provided (refer to ).
- For multi-axis assemblies, always lift the system by the lower axis.
- Use a cart, dolly, or similar device to move the stage to a new location.

Gently set the stage on a smooth, flat, and clean surface. Use compressed nitrogen or clean, dry, oil-free air to remove any dust or debris that has collected during shipping.

Before you operate the stage, let it stabilize at room temperature for at least 12 hours. This will ensure that all of the alignments, preloads, and tolerances are the same as they were when they were tested at Aerotech.

Each stage has a label listing the system part number and serial number. These numbers contain information necessary for maintenance or system hardware and software updates. Locate this label and record the information for later reference.

### **Storage**

Store the stage in the original shipping container. If the original packaging included ESD protective packaging, make sure to store the stage in it. The storage location must be dry, free of dust, free of vibrations, and flat.

Refer to [Section 1.1. Environmental Specifications](#)

## Chapter 1: Overview

**Table 1-1: Model Numbers and Ordering Options**

<b>ATX1156SL/SLE Mechanical-Bearing Screw-Driven Linear Stage</b>	
<b>Direct Linear Feedback (Required)</b>	
SL	No direct linear feedback
SLE-E1	Incremental linear encoder, 1 Vpp
SLE-E2	Incremental linear encoder, 0.05 $\mu$ m digital TTL output
SLE-E3	Absolute linear encoder
<b>Travel (Required)</b>	
-050	50 mm travel stage
-100	100 mm travel stage
-150	150 mm travel stage
<b>Motor (Optional)</b>	
-M1	DC servomotor with 10,000-line TTL encoder
-M2	DC servomotor with 10,000-line TTL encoder and brake
-M3	DC servomotor with 1,000-line 1 Vpp encoder
-M4	DC servomotor with 1,000-line 1 Vpp encoder and brake
-M5	Stepper motor
<b>Foldback Kit (Optional)</b>	
-FB1	Foldback kit
<b>ThermoComp™ (Optional)</b>	
-TCMP	ThermoComp™ integrated thermal compensation
<b>NOTE:</b> You must use an Automation1 or A3200 controller with the -TCMP option.	
<b>Metrology (Required)</b>	
-PL1	Uncalibrated with performance plots
-PL2	Calibrated (HALAR) with performance plots

## 1.1. Environmental Specifications



**WARNING: General Hazard Warning!** Do not expose this product to environments or conditions outside of the listed specifications. You could damage the equipment if you exceed the environmental or operating specifications.



**DANGER: Risk in Explosive Atmosphere!**

- Standard Aerotech stage/motors are not rated for applications with explosive atmospheres such as airborne dust or combustible vapors.
- Do not operate stage/motors outside of Aerotech environmental specifications.

**Table 1-2: Environmental Specifications**

<b>Ambient Temperature</b>	Operating: 10 °C to 35 °C (50 °F to 95 °F)
	The optimal operating temperature is 20 °C ±2 °C (68 °F ±4 °F). If at any time the operating temperature deviates from 20 °C degradation in performance could occur.
<b>Humidity</b>	Storage: 0 °C to 40 °C (32 °F to 104 °F) in original shipping packaging
	Operating: 20% to 60% RH Storage: 10% to 70% RH, non-condensing in original packaging. The stage should be packaged with desiccant if it is to be stored for an extended time.
<b>Altitude</b>	Operating: 0 m to 2,000 m (0 ft to 6,562 ft) above sea level
	Contact Aerotech if your specific application involves use above 2,000 m or below sea level.
<b>Vibration</b>	Use the system in a low vibration environment. Floor or acoustical vibration can affect system performance. Contact Aerotech for information regarding your specific application.
<b>Protection Rating</b>	These stages have an ingress protection rating of IP10.
<b>Use</b>	Indoor use only

## 1.2. Accuracy and Temperature Effects

Aerotech products are designed for and built in a 20°C (68°F) environment. Temperature changes could cause a decrease in performance or permanent damage to the stage. At a minimum, the environmental temperature must be controlled to within 0.25°C per 24 hours to ensure the stage specifications are repeatable over an extended period of time. The severity of temperature effects on all specifications depends on many different environmental conditions, which include how the stage is mounted. Contact the factory for more details.

The accuracy specification of stage is measured 25 mm above the table with the stage in an unloaded condition. The stage is assumed to be fully supported by a mounting surface meeting or exceeding the specification in [Section 2.2](#).

The accuracy of the screw is a key element in the overall positioning accuracy of the SL stage. A scale error can be expected if temperature of the screw differs from 20° C (68° F). The greater the temperature difference, the greater the error. The temperature of the screw depends on the speed and duty cycle of the stage. The faster the movement and higher the duty cycle, the more the stage accuracy will be affected by heat. The thermal expansion coefficient of the screw is 11.7 ppm/°C.

SLE stages contain a linear encoder for direct feedback of the carriage position. The stage travel as seen by the linear encoder will expand at the rate of 3.25 ppm/°C as the temperature of the encoder scale deviates from 20°C.

The ThermoComp™ option is a hardware and software solution that uses the functionality of the Automation1 or A3200 controller to mitigate the effects of changing temperature by detecting and compensating for thermal changes. ThermoComp™ is effective at compensating for both self-heating and environmental temperature changes.

### 1.3. Basic Specifications

Resolution is dependent on screw pitch, encoder resolution, and controller interpolation.

**Table 1-3: ATX115SL/SLE Series Specifications**

			-050	-100	-150
Travel			50 mm	100 mm	150 mm
Accuracy <sup>(1)</sup>	SL	Uncalibrated	±6 µm	±6 µm	±7 µm
		Calibrated <sup>(2)</sup>	±0.75 µm	±1 µm	±1 µm
	SLE	Uncalibrated	±2 µm	±3 µm	±4 µm
		Calibrated <sup>(2)</sup>	±0.5 µm	±0.6 µm	±0.6 µm
Resolution (Minimum Incremental Motion) <sup>(8)</sup>	SL		0.05 µm <sup>(3)</sup>		
			0.1 µm <sup>(4)</sup>		
	SLE	-E1 <sup>(6)</sup>	0.025 µm		
		-E2	0.1 µm		
-E3		0.2 µm			
Bidirectional Repeatability <sup>(1)</sup>	SL		±0.5 µm		
	SLE		±0.15 µm	±0.2 µm	±0.2 µm
Horizontal Straightness <sup>(1)</sup>			±1.25 µm	±1.5 µm	±1.75 µm
Vertical Straightness <sup>(1)</sup>			±1.25 µm	±1.5 µm	±1.75 µm
Pitch			60 µrad (12 arc-sec)	70 µrad (14 arc-sec)	80 µrad (16 arc-sec)
Yaw			40 µrad (8 arc-sec)	50 µrad (10 arc-sec)	60 µrad (12 arc-sec)
Ball Screw Lead			2 mm/rev		
Maximum Speed <sup>(5)</sup>	DC Motor (-M1, -M2)		100 mm/s		
	DC Motor (-M3, -M4)		220 mm/s		
	Stepper Motor (-M5)		60 mm/s		
Load Capacity	Horizontal		14 kg		
	Side		10 kg		
	Vertical (Axial)		7 kg		
Moving Mass			0.8 kg	1.0 kg	1.3 kg
Stage Mass			3.2 kg	3.8 kg	4.5 kg
Material			Anodized Aluminum		
1. Certified with each stage. 2. Available with Aerotech controllers. 3. Achieved with Aerotech rotary motor with amplified sine encoder. The specification is unidirectional. 4. Achieved with Aerotech rotary motor with 10,000 lines/rev digital encoder. The specification is unidirectional. 5. Requires the selection of an applicable amplifier with sufficient voltage and current. 6. Requires a motor with a 1 Vpp amplified sine encoder (-M3 and -M4 Motor Options) and linear amplifier. 7. Specifications listed are non-foldback kit options. Contact the factory for specifications when a foldback kit (-FBx) is used.					

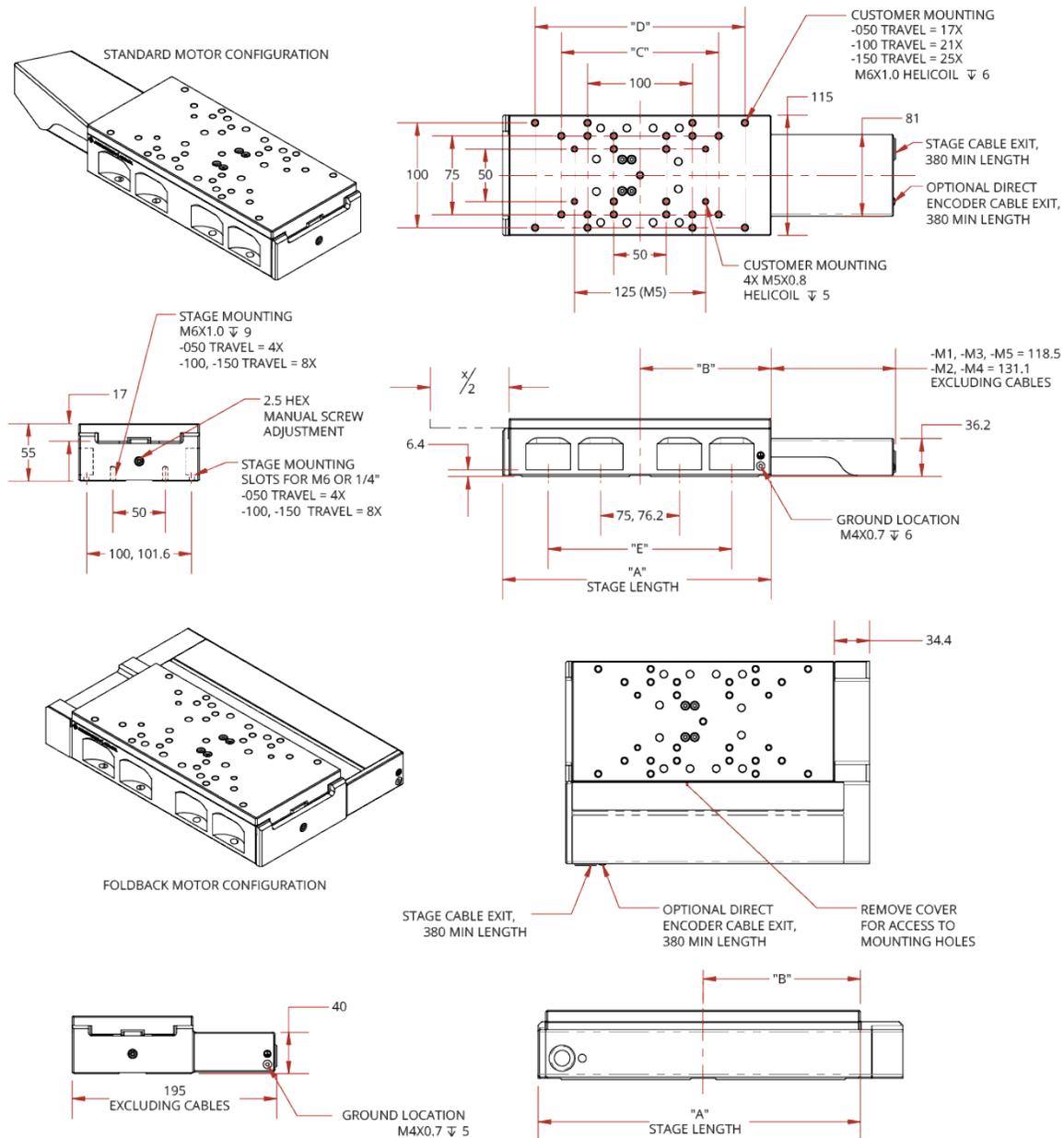
# Chapter 2: Installation



**IMPORTANT:** The stage installation must be in accordance with the instructions provided by this manual and any accompanying documentation. Failure to follow these instructions could result in injury or damage to the equipment.

## 2.1. Dimensions

Figure 2-1: ATX115SL/SLE Dimensions



BASIC MODEL	NOMINAL TRAVEL x	ELEC LIMIT TRAVEL	MECH LIMIT TRAVEL	A	B	C	D	E
ATX115SL-050	50	53	57	156	75	-	-	-
ATX115SL-100	100	103	107	206	100	150	-	125, 127
ATX115SL-150	150	153	157	256	125	150	200	175, 177.8

DIMENSIONS: MILLIMETERS



## 2.2. Securing the Stage to the Mounting Surface



**DANGER: Mechanical Hazard!**

Personnel must be made aware of the mechanical hazards during set up or when you do service to the stage.

- Do not manually move the stage if it is connected to a power source.
- The stage must be mounted securely. Improper mounting can result in injury and damage to the equipment.
- When you move the tabletop manually to do maintenance, this could expose the operator to pinch points. Refer to [Pinch Points](#) on [Page 12](#).

The mounting surface must be flat and have adequate stiffness to achieve the maximum performance from the stage. When it is mounted to a non-flat surface, the stage can be distorted while the mounting screws are tightened. This distortion will decrease overall accuracy. Adjustments to the mounting surface must be done before the stage is secured.

Inspect the mounting surface for dirt or unwanted residue and clean if necessary. Use precision flatstones on the mounting surface to remove any burrs or high spots. Clean the mounting surface with a lint-free cloth and acetone or isopropyl alcohol and allow the cleaning solvent to completely dry. Gently place the stage on the mounting surface.



**IMPORTANT:** The stage is precision machined and verified for flatness prior to product assembly at the factory. If machining is required to achieve the desired flatness, it should be performed on the mounting surface rather than the stage. Shimming should be avoided if possible. If shimming is required, it should be minimized to retain maximum rigidity of the system.

**Table 2-1: Stage Mounting Surface Flatness Requirement**

Stage Travel	Flatness Requirement
All Travels	7.5 µm

If necessary, manually move the stage table to access the mounting holes along the edges of the stage. This stage is designed to use socket head cap screws (SHCS) to secure the base to the mounting surface.



**IMPORTANT:** The stage table may offer a considerable amount of resistance when it is moved manually.

- Do not attempt to manually move the stage if it is connected to a power source or includes an integrated brake.

Tightening torque values for the mounting hardware are dependent on the properties of the surface to which the stage is being mounted. Values provided in [Table 2-2](#) are typical values and may not be accurate for your mounting surface. Refer to [Section 2.1](#) for mounting locations and dimensions.

**Table 2-2: Stage to Mounting Surface Hardware**

Mounting Hardware	Typical Screw Torque
Factory provided M6 x 16 mm (or 1/4" x 3/4") low head SHCS with flat washers	7 N·m [5 ft·lb]

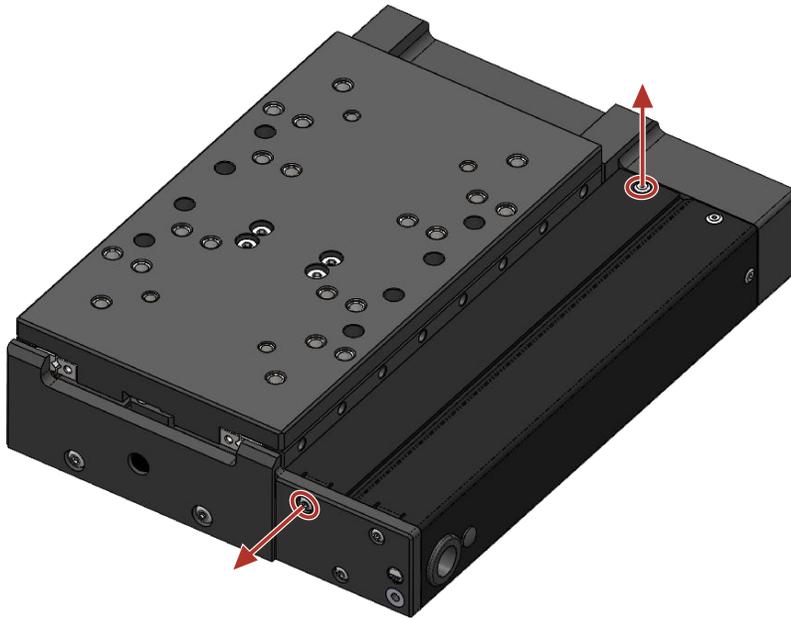
If you use the mounting slots, use the provided stubby ball end hex key to tighten the mounting bolts (Figure 2-2).

**Figure 2-2: Stubby Ball End Hex Key**

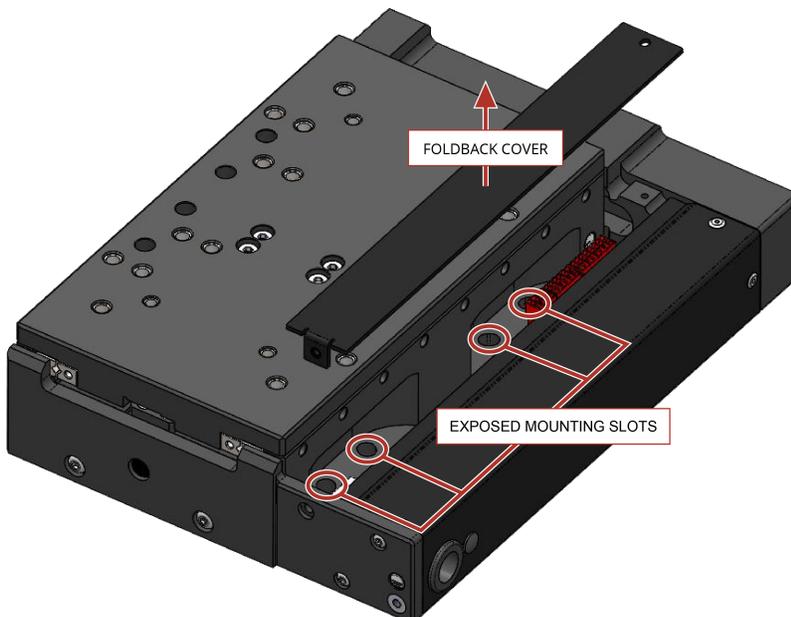


For foldback stages, you will have to remove part of the foldback cover to access all of the mounting slots. Remove the two screws that secure the mounting access foldback cover (Figure 2-3) and lift the cover to access the mounting holes (Figure 2-4). After installation of the mounting screws, replace the cover and screws.

**Figure 2-3: Foldback Cover Screw Locations**



**Figure 2-4: Foldback Motor Mounting Slot Locations**



### 2.3. Attaching the Payload to the Stage

Inspect the mounting surface for dirt or unwanted residue and clean if necessary. Clean the mounting surface with a lint-free cloth and acetone or isopropyl alcohol and allow the cleaning solvent to completely dry. Gently place the stage on the mounting surface.

Use a representative payload during start-up to prevent accidental damage to the stage and the payload. Proceed with the electrical installation and test the motion control system in accordance with the system documentation. Document all results for future reference. For information on electrical installation refer to [Chapter 3: Electrical Installation](#) and the documentation delivered with the stage.



**IMPORTANT:** If your ATX115SL/SLE was purchased with Aerotech controls, it could have been tuned with a representative payload based on the information provided at the time of order. If you start the ATX115SL/SLE without a payload, the servo gains provided by Aerotech with the shipment may not be appropriate and servo instability can occur. Refer to the controller help file for tuning assistance.

The payload must be flat, rigid, and comparable to the stage in quality to maintain optimum performance.

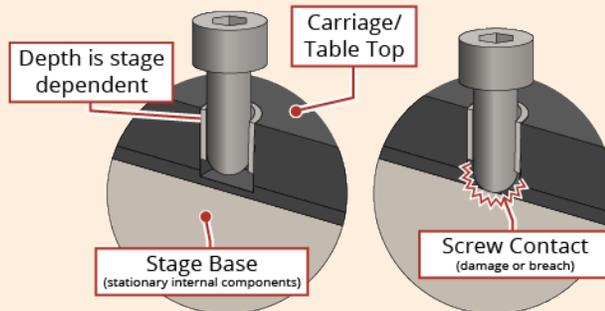
**Table 2-3: Payload Mounting Surface Flatness Requirement**

Stage Travel	Flatness Requirement
All Travels	7.5 µm

**WARNING: General Hazard Warning!**

Be careful when you attach the payload to the stage mounting surface.

- If a mounting screw extends through the carriage/table top, it can affect travel and damage the stage.
- Refer to the dimensions in [Section 2.1](#) for maximum allowable thread engagement.
- **Mounting Hole Cutaway:**



Applied loads should be symmetrically distributed whenever possible. The payload should be centered on the stage mounting surface and the entire stage should be centered on the support structure.

For a cantilevered load, first determine if it is a **Vertical**, **Horizontal**, or a **Side** cantilever system (refer to [Figure 2-5](#)).

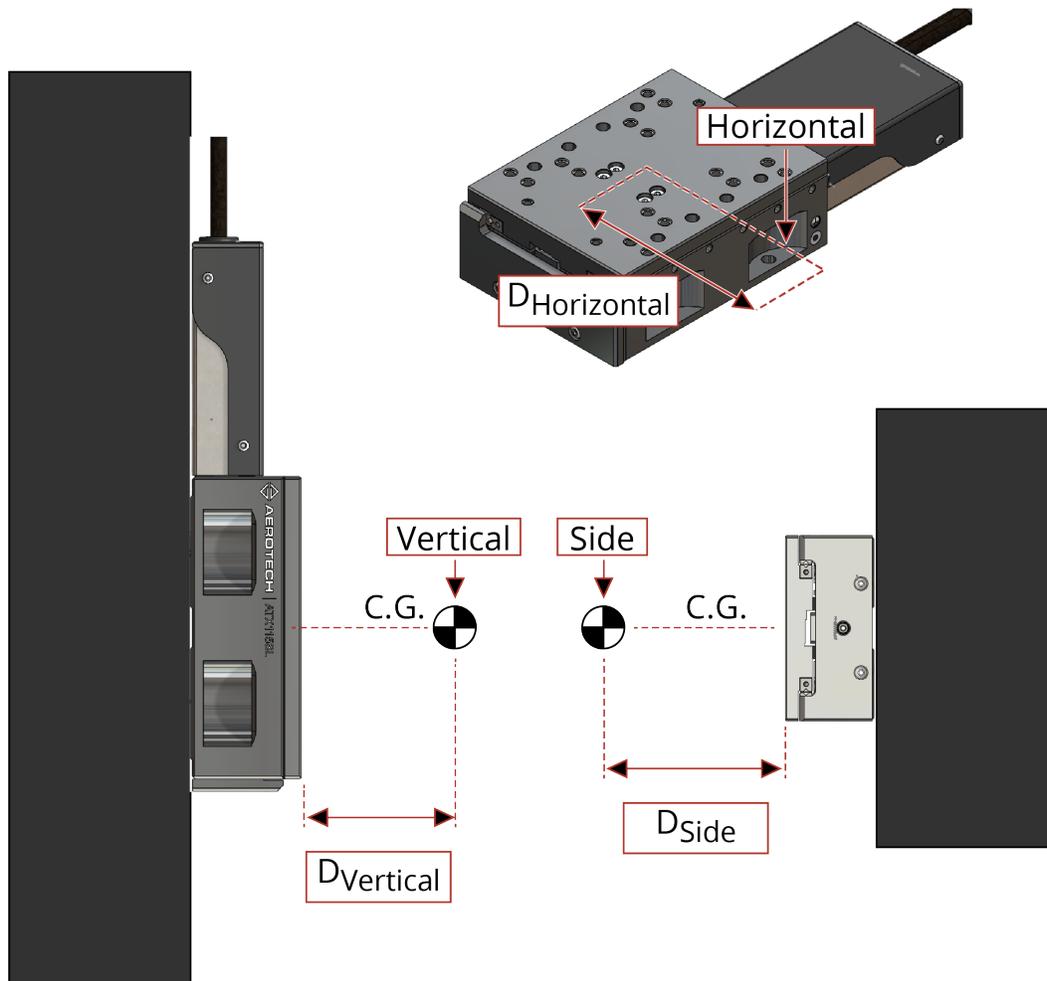
The **Vertical** curve is for situations where the stage is mounted in a vertical orientation and the payload is mounted to the table top with its center of gravity extended outward in a direction normal to the tabletop surface. Refer to [Figure 2-7](#) or [Figure 2-8](#) for torque requirements on a vertical orientation.

The **Horizontal** curve assumes a horizontal stage orientation with the payload offset extending outwards along the surface of the tabletop.

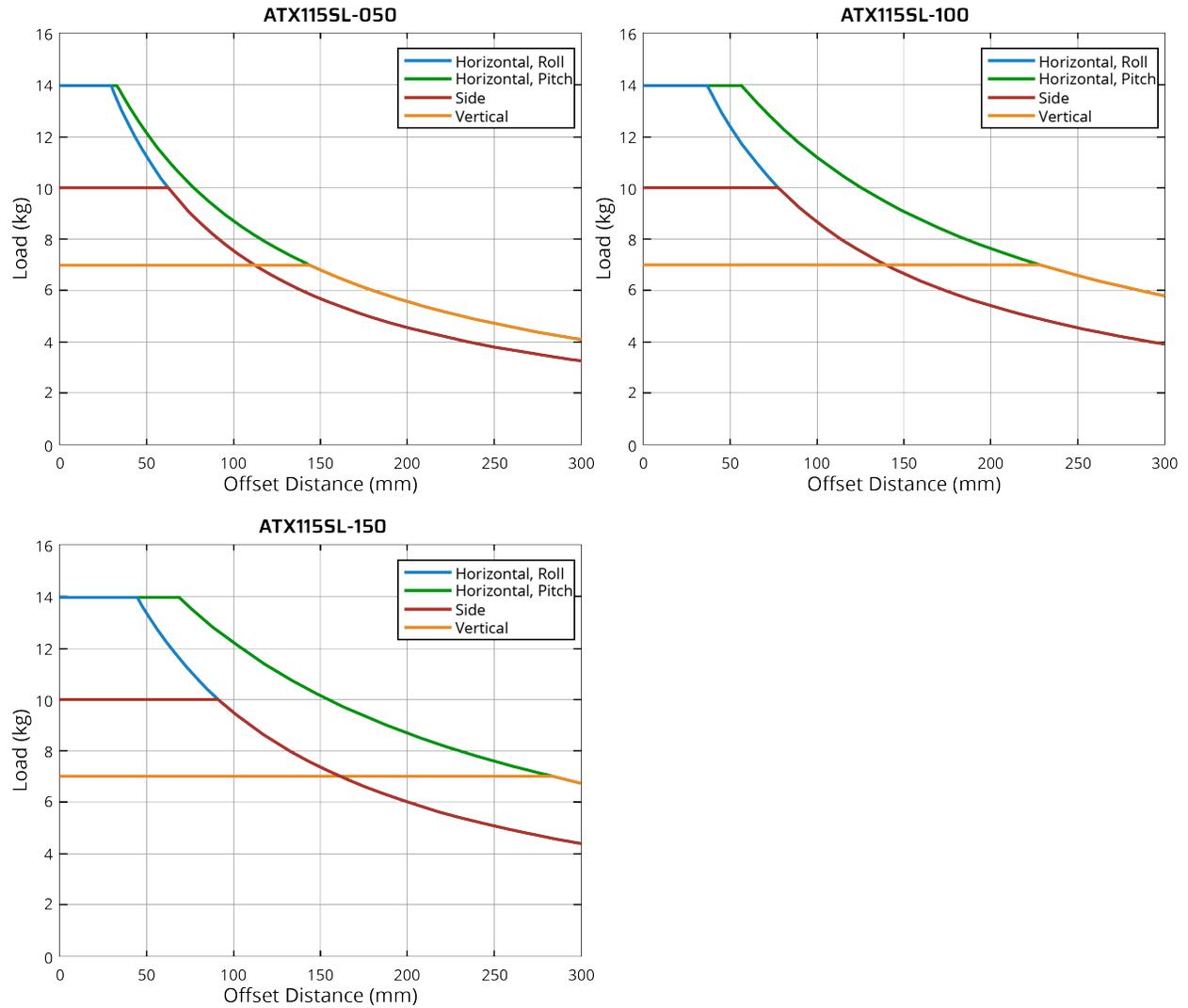
The **Side** curve is for situations where the stage is mounted on its side and the offset load extends outwards in a direction normal to the tabletop surface.

Measure the cantilever length, then find the corresponding load value from [Figure 2-6](#).

**Figure 2-5: Stage Orientations**



**Figure 2-6: Cantilevered Load Capability**



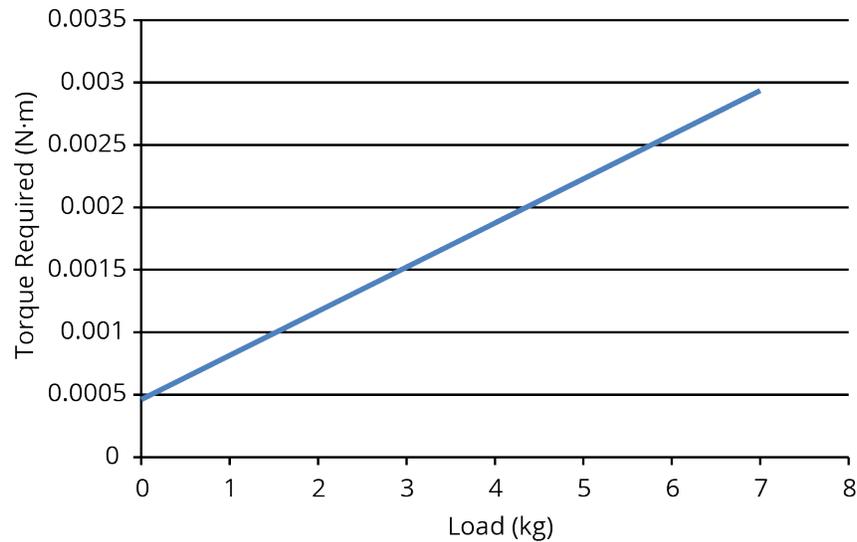
The approximate amount of torque required to turn the ball screw of ATX115SL/SLE series stages can be found from [Figure 2-8](#) or the following equation:

**Figure 2-7: Load Torque Equation**

$$Torque_{REQ} = \frac{(AxialLoad) \times (LeadofScrew)}{2 \times \pi \times (Efficiency)}$$

For ATX115SL/SLE series stages, the ball screw efficiency is rated at 90% (0.90). Refer to [Section 1.3](#) for Load Capacity specifications.

**Figure 2-8: Torque Required to Turn Ball Screw in Vertical Orientation**



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## Chapter 3: Electrical Installation

### **DANGER: Electrical Shock Hazard!**



- Stage motor phase voltage levels could be hazardous live.
- Personnel are protected from hazardous voltages unless electrical interconnections, protective bonding (safety ground), or motor/stage enclosures are compromised.
- Do not connect or disconnect stage/motor interconnections while connected to a live electrical power source.
- Before you set up or do maintenance, disconnect electrical power.
- It is the responsibility of the End User/System Integrator to make sure that stages are properly connected and grounded per Engineering Standards and applicable safety requirements.
- It is the responsibility of the End User/System Integrator to configure the system drive or controller within the Aerotech motor/stage electrical and mechanical specifications.

### **WARNING: General Hazard Warning!**



Applications that require access to the ATX115SL/SLE must be restricted to qualified and trained personnel. The system integrator or qualified installer is responsible for determining and meeting all safety and compliance requirements when they integrate the ATX115SL/SLE into a completed system. Failure to do so could expose the operator to electrical or mechanical hazards.

Electrical installation requirements will depend on the ordered product options. Installation instructions in this section are for Aerotech products equipped with standard Aerotech motors intended for use with an Aerotech motion control system. Contact Aerotech for further information on products that are otherwise configured.

Aerotech motion control systems are adjusted at the factory for optimum performance. When the ATX115SL/SLE is part of a complete Aerotech motion control system, setup should only require that you connect the stage to the appropriate drive chassis with the cables provided. Labels on the system components should indicate the appropriate connections.

If system level integration was purchased, an electrical drawing that shows the system interconnects has been supplied with the system (separate from this documentation).

The electrical wiring from the motor and encoder are integrated at the factory. Refer to the sections that follow for standard motor wiring and connector pinouts.



**IMPORTANT:** Refer to the controller documentation to adjust servo gains for optimum velocity and position stability.

### 3.1. Motor and Feedback Connectors

Stages equipped with standard motors and encoders come from the factory completely wired and assembled.



**IMPORTANT:** Refer to the other documentation accompanying your Aerotech equipment. Call your Aerotech representative if there are any questions on system configuration.



**IMPORTANT:** If you are using standard Aerotech motors and cables, motor and encoder connection adjustments are not required.



**IMPORTANT:** The ATX115SL/SLE requires two encoder feedback channels. When used with the Lab controller, the second encoder channel will require a second axis and an adapter cable. The motor output of the second axis will not be available to drive a motor.

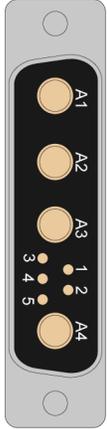
The protective ground connection of the ATX115SL/SLE provides motor frame ground protection only. Additional grounding and safety precautions are required for applications requiring access to the stage while it is energized. The System Integrator or qualified installer is responsible for determining and meeting all safety and compliance requirements necessary for the integration of this stage into the final application.



**DANGER: Electrical Shock Hazard!**

- The protective ground connection must be properly installed to minimize the possibility of electric shock.
- The stage controller must provide over-current and over-speed protection. Failure to do so could cause electric shock or damage to the equipment.

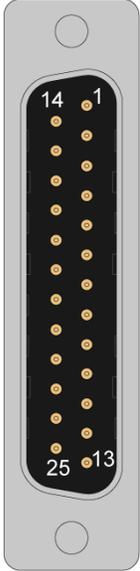
**Table 3-1: 4-Pin Motor Connector Pinout for the -M1 through -M4 Options**

Pin	Description	Connector
Case	Shield Connection	
A1	DC+	
A2	Reserved	
A3	DC-	
1	Reserved	
2	Reserved	
3	Reserved	
4	Reserved	
5	Reserved	
A4	Frame Ground (motor protective ground)	

**Table 3-2: 4-Pin Motor Mating Connector Part Numbers**

Mating Connector	Aerotech P/N	Third Party P/N
Backshell	ECK00656	Amphenol #17E-1726-2
Sockets [QTY. 4]	ECK00659	ITT Cannon #DM53744-6
Connector	ECK00657	ITT Cannon #DBM9W4SA197

**Table 3-3: 25-Pin Feedback Connector Pinout for the -M1 through -M4 Options**

Pin	Description	Connector
Case	Shield Connection	
1	Reserved	
2	Reserved	
3	5V Power Supply Input (PIN 3 is internally connected to PIN 16)	
4	Reserved	
5	Reserved	
6	MRK- (Encoder Marker-)	
7	MRK+ (Encoder Marker+)	
8	Reserved	
9	Reserved	
10	Reserved	
11	Reserved	
12	+/CW LMT (End-of travel limit signal that indicates maximum permitted stage travel in the “machine positive” or “machine clockwise” direction.)	
13	Brake - (-M2 or -M4 option only)	
14	COS+ (Encoder Cosine+)	
15	COS- (Encoder Cosine-)	
16	5V Power Supply Input (PIN 16 is internally connected to PIN 3)	
17	SIN+ (Encoder Sine+)	
18	SIN- (Encoder Sine-)	
19	Reserved	
20	5 V Supply Common, 0V (PIN 20 is connected internally to PIN 21)	
21	5 V Supply Common, 0V (PIN 21 is connected internally to PIN 20)	
22	Reserved	
23	Reserved	
24	-/CCW LMT (End-of travel limit signal that indicates maximum permitted stage travel in the “machine negative” or “machine counter-clockwise” direction.)	
25	Brake + (-M2 or -M4 option only)	

**Table 3-4: 25-Pin Feedback Mating Connector Part Numbers**

Mating Connector	Aerotech P/N	Third Party P/N
25-Socket D-Connector	ECK00300	FCI DB25S064TLF
Backshell	ECK00656	Amphenol 17E-1726-2

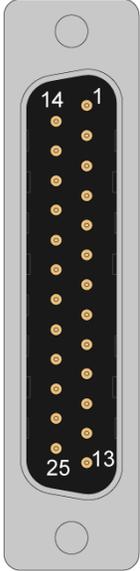
**Table 3-5: 4-Pin Motor Connector Pinout for the -M5 Option**

Pin	Description	Connector
A1	Motor Phase A	
A2	Motor Phase B	
A3	Motor Phase A Return	
1	Reserved	
2	Reserved	
3	Reserved	
4	Frame Ground (motor protective ground)	
5	Frame Ground (motor protective ground)	
A4	Motor Phase B Return	

**Table 3-6: 4-Pin Motor Mating Connector Part Numbers**

Mating Connector	Aerotech P/N	Third Party P/N
Backshell	ECK00656	Amphenol #17E-1726-2
Sockets [QTY. 4]	ECK00659	ITT Cannon #DM53744-6
Connector	ECK00657	ITT Cannon #DBM9W4SA197

**Table 3-7: 25-Pin Feedback Connector Pinout for the -M5 Option**

Pin	Description	Connector
Case	Shield Connection	
1	Reserved	
2	Reserved	
3	5V Power Supply Input (PIN 3 is internally connected to PIN 16)	
4	Reserved	
5	Reserved	
6	Reserved	
7	Reserved	
8	Reserved	
9	Reserved	
10	Reserved	
11	Reserved	
12	+ /CW LMT (End-of travel limit signal that indicates maximum permitted stage travel in the “machine positive” or “machine clockwise” direction.)	
13	Reserved	
14	Reserved	
15	Reserved	
16	5V Power Supply Input (PIN 16 is internally connected to PIN 3)	
17	Reserved	
18	Reserved	
19	Reserved	
20	5 V Supply Common, 0 V (PIN 20 is connected internally to PIN 21)	
21	5 V Supply Common, 0 V (PIN 21 is connected internally to PIN 20)	
22	Reserved	
23	Reserved	
24	- /CCW LMT (End-of travel limit signal that indicates maximum permitted stage travel in the “machine negative” or “machine counter-clockwise” direction.)	
25	Reserved	

**Table 3-8: 25-Pin Feedback Mating Connector Part Numbers**

Mating Connector	Aerotech P/N	Third Party P/N
25-Socket D-Connector	ECK00300	FCI DB25S064TLF
Backshell	ECK00656	Amphenol 17E-1726-2

**Table 3-9: 15-Pin Linear Encoder Connector Pinout (-SLE1/-SLE2)**

Pin	Description	Connector
Case	Shield Connection	
1	Reserved	
2	5 V Supply Common, 0 V (PIN 2 is connected internally to PIN 9)	
3	Reserved	
4	MRK- (Encoder Marker-)	
5	SIN- (Encoder Sine-)	
6	COS- (Encoder Cosine-)	
7	5V Power Supply Input (PIN 7 is internally connected to PIN 8)	
8	5V Power Supply Input (PIN 8 is internally connected to PIN 7)	
9	5 V Supply Common, 0 V (PIN 9 is connected internally to PIN 2)	
10	Reserved	
11	Reserved	
12	MRK+ (Encoder Marker+)	
13	SIN+ (Encoder Sine+)	
14	COS+ (Encoder Cosine+)	
15	Reserved	

**Table 3-10: 15-Pin Linear Encoder Connector Pinout (-SLE3)**

Pin	Description	Connector
Case	Shield Connection	
1	Reserved	
2	5 V Supply Common, 0 V	
3	Reserved	
4	5 V Supply Input +	
5	DAT+ (Data +)	
6	Reserved	
7	Reserved	
8	CLK+ (Clock +)	
9	Reserved	
10	Reserved	
11	Reserved	
12	Reserved	
13	DAT- (Data -)	
14	COS+ (Encoder Cosine+)	
15	CLK- (Clock -)	

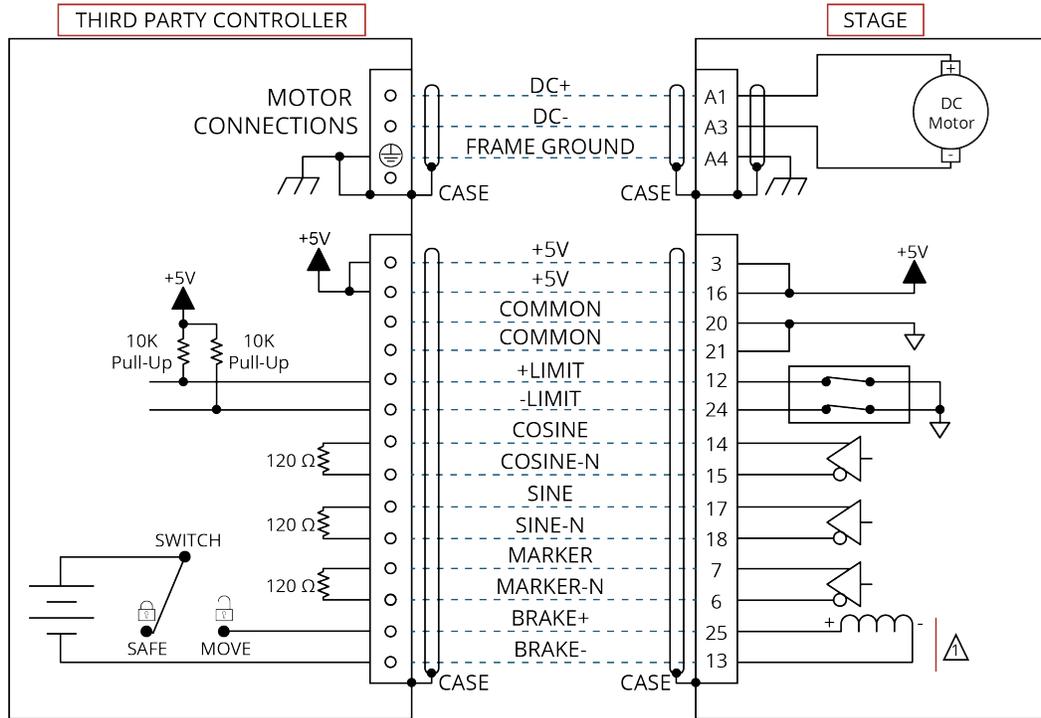
**Table 3-11: 15-Pin Mating Connector Part Numbers**

Mating Connector	Aerotech P/N	Third Party P/N
15-Socket D-Connector	ECK01022	Amphenol 17E-1725-2
Backshell	ECK00326	Amphenol DA15S064TLF

### 3.2. Motor and Feedback Wiring

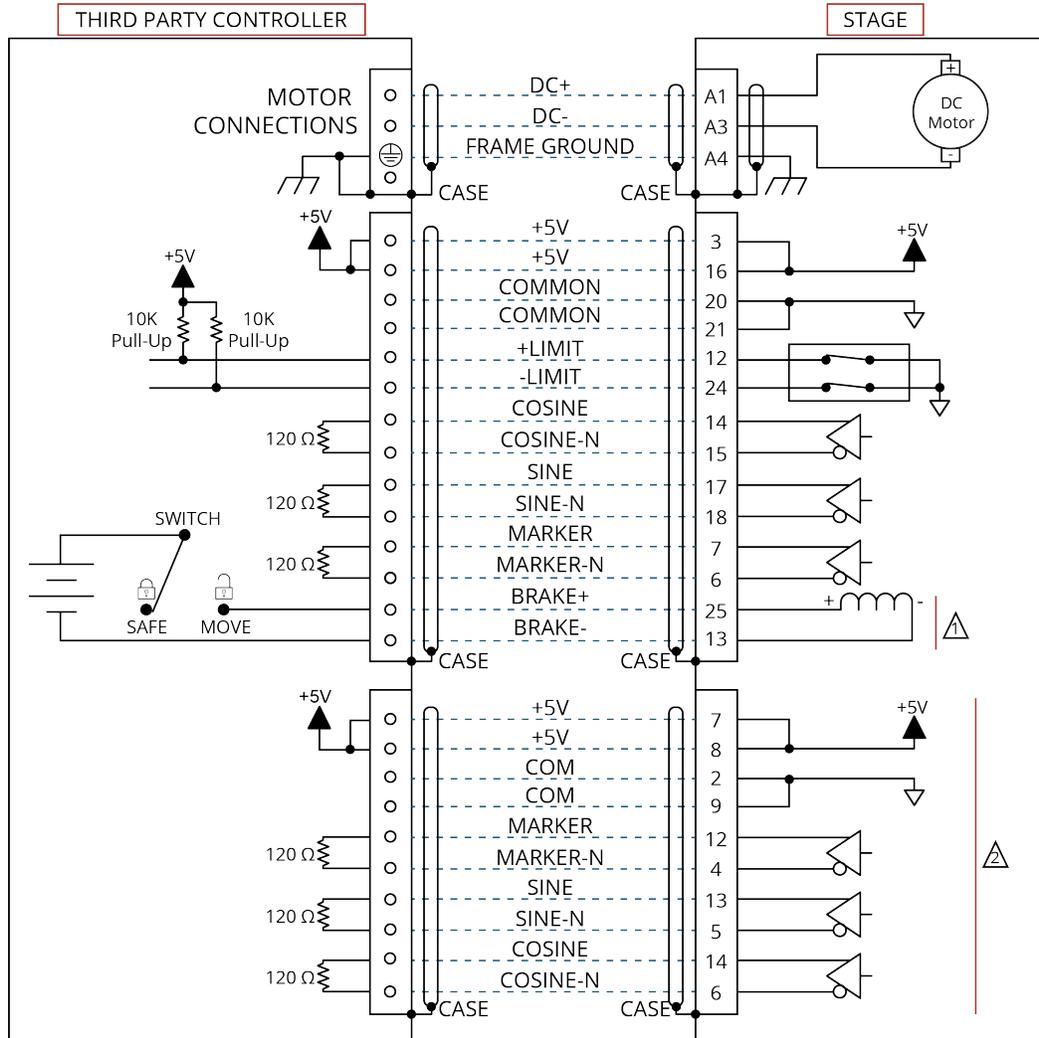
Shielded cables are required for the motor and feedback connections.

**Figure 3-1: ATX115SL DC Motor and Feedback Wiring**



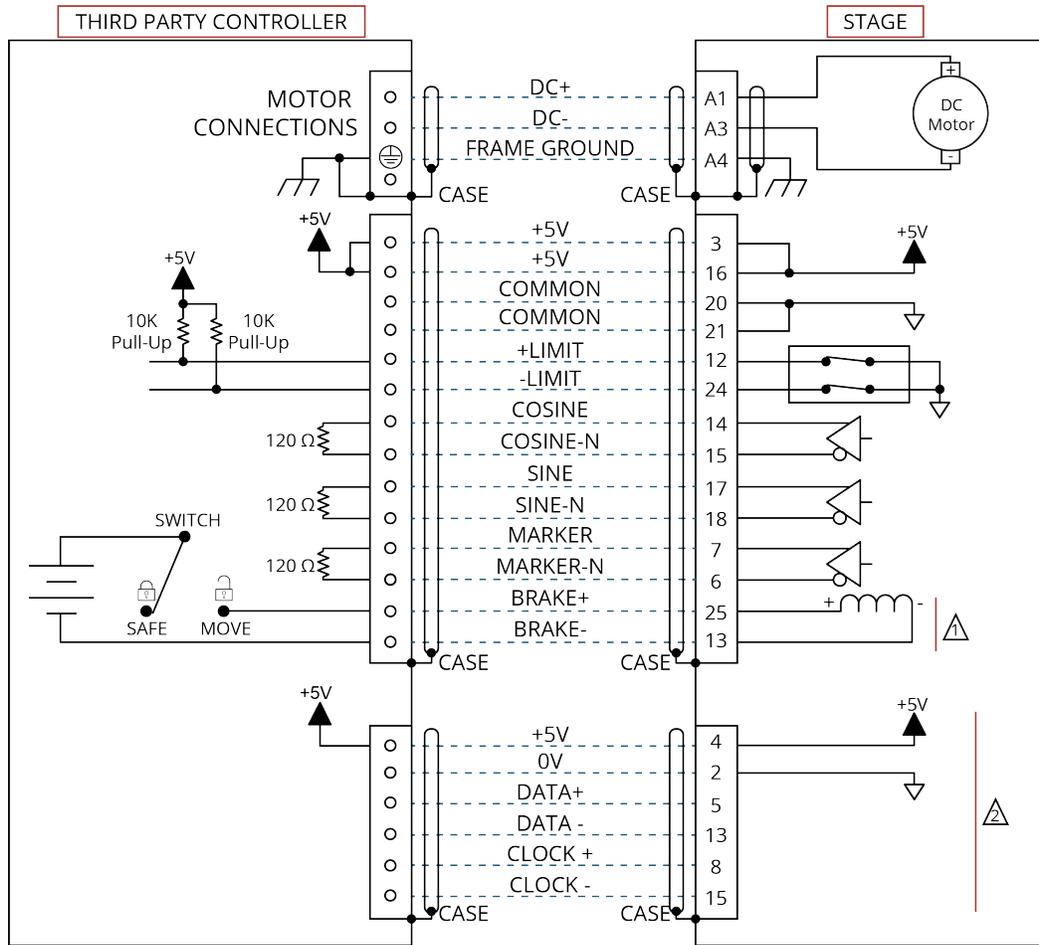
 Brake is only available on -M2 and -M4 options.

Figure 3-2: ATX115SLE-E1 and -E2 DC Motor and Feedback Wiring



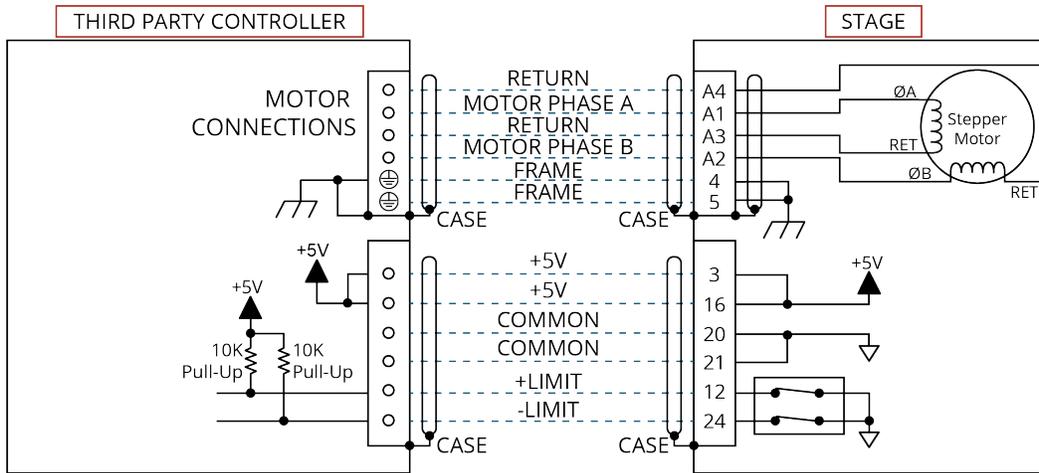
- ⚠ Brake is only available on -M2 and -M4 options.
- ⚠ -SLE-E1 and -SLE-E2 encoder option connector

Figure 3-3: ATX115SLE-E3 DC Motor and Feedback Wiring

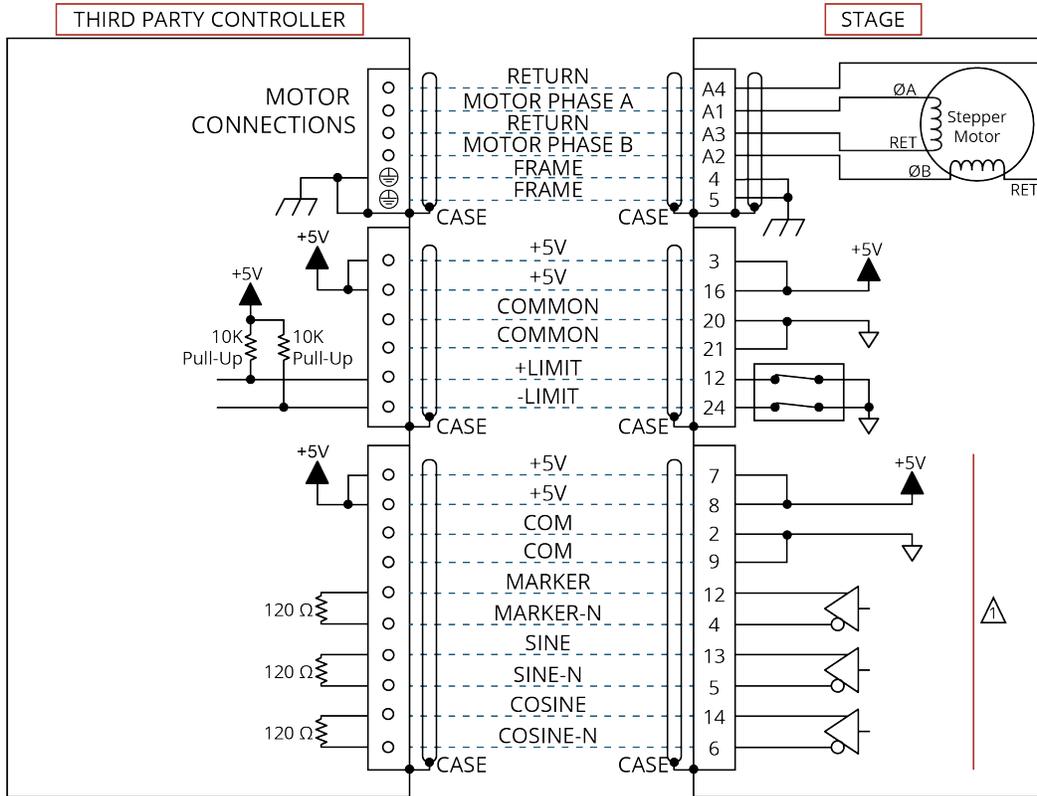


- ⚠ Brake is only available on -M2 and -M4 options.
- ⚠ -SLE-E3 encoder option connector

**Figure 3-4: ATX115SL Stepper Motor and Feedback Wiring**

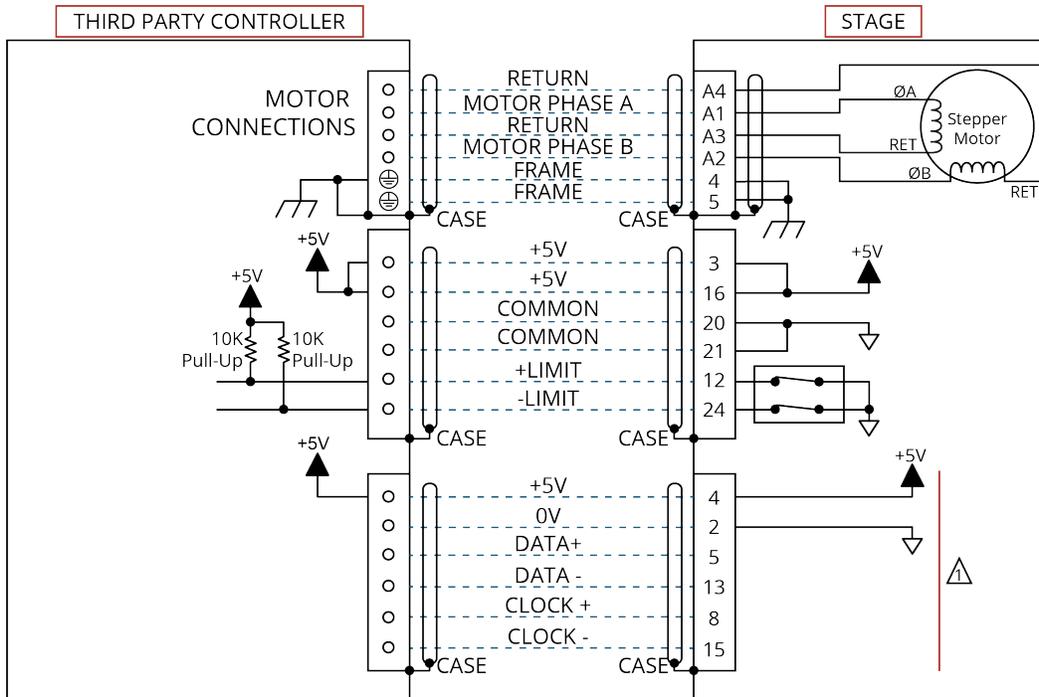


**Figure 3-5: ATX115SLE-E1 and -E2 Stepper Motor and Feedback Wiring**



 -SLE-E1 and -SLE-E2 encoder option connector

Figure 3-6: ATX115SLE-E3 Stepper Motor and Feedback Wiring



⚠ -SLE-E3 encoder option connector

### 3.3. Motor and Feedback Specifications



**IMPORTANT:** All 5 V supplies share one common connection within the stage.

**Table 3-12: Hall-Effect Sensor Specifications**

	Specification
Supply Voltage	5 V $\pm$ 5%
Supply Current	50 mA
Output Type	Open Collector
Output Voltage	24 V max (pull up)
Output Current	5 mA (sinking)

**Table 3-13: Thermistor Specifications (BMS Motor Options)**

	Specification
Polarity	Logic "0" (no fault)
	Logic "1" (over-temperature fault)
Cold Resistance	$\sim$ 100 $\Omega$
Hot Resistance	$\sim$ 10 K
<b>Note:</b> 1K pull-up to +5V recommended.	

**Table 3-14: Encoder Specifications**

	Specification
Supply Voltage	5 V $\pm$ 5%
Supply Current	250 mA (typical)
Output Signals (Differential)	<b>Sinusoidal Type (Incremental Encoder):</b> Analog: SIN+, SIN-, COS+, COS-, 1V <sub>pk-pk</sub> ; Digital (RS422): MRK+, MRK- signals.
	<b>Digital Output (Incremental Encoder):</b> TTL Encoder line-driver signals; RS422/485 compatible
	<b>Serial Output (Absolute Encoder):</b> EnDat 2.2 with 36 bit word

**Table 3-15: Rotary Encoder Resolution Specifications**

Encoder Option	Fundamental Signal Period	Digital Resolution
-M1, -M2 (10,000 line TTL signal)	200 nm	50 nm
-M3, -M4 (1,000 line 1 Vpp Amplified Sine signal)	2000 nm	500 nm
-M3, -M4 with 1000x Interpolation <sup>(1)</sup> (1000 line 1 Vpp Amplified Sine signal)	2 nm	0.5 nm
-M3, -M4 with 4000x Interpolation <sup>(1)</sup> (1000 line 1 Vpp Amplified Sine signal)	0.5 nm	0.125 nm
1. Quadrature decoding included in interpolated resolution calculations		

**Table 3-16: Limit Switch Specifications**

	Specification
Supply Voltage	5 V $\pm$ 5%
Supply Current	25 mA
Output Type	Open Collector, Current Sinking, 24 VDC Max., 25 mA max.
Output Polarity (Factory Configured)	<b>Normally Closed (NC)</b> <ul style="list-style-type: none"> <li>Sinks current to ground (Logic "0") when not in limit (limit not active).</li> <li>High impedance (Logic "1") when in limit (limit active).</li> <li>Third party controller LIMIT inputs typically require 10 k<math>\Omega</math> pull-up to logic VDC supply.</li> </ul>
<b>Note:</b> <ul style="list-style-type: none"> <li>If the ATX115SL/SLE is driven beyond the electrical limit, it will encounter a mechanical stop. Impacting the mechanical stop could cause damage to the stage, even at low speeds.</li> <li>Refer to <a href="#">Section 3.2. Motor and Feedback Wiring</a> for LIMIT circuit descriptions.</li> </ul>	

**Table 3-17: Brake Specifications**

	Specification
Supply Voltage	24 VDC
Supply Current (typical)	1.0 A (current required to release the brake and allow motion)

**Table 3-18: ATX115SL/SLE DC Motor Specifications**

		DC Servomotor
<b>Performance Specifications</b>		
Stall Torque, Continuous	N·m (oz·in)	0.068 (9.6)
Peak Torque	N·m (oz·in)	0.656 (93)
Maximum Speed	rpm	10,000
Rated Power	W (hp)	52.5 (0.07)
<b>Electrical Specifications</b>		
Continuous Stall Current	A	2.8
Torque Constant	N·m/A (oz·in/A)	0.0289 (4.1)
Terminal Resistance	$\Omega$	1.03
BEMF Constant	V/krpm	3.02
Armature Inductance	mH	0.158
Armature Moment of Inertia	kg·m <sup>2</sup> (oz·in·s <sup>2</sup> )	2.5 $\times$ 10 <sup>-6</sup> (0.00033)
Recommended Bus Voltage	VDC	24
Maximum Terminal Voltage	VDC	48
Motor Constant	N·m/ $\sqrt$ W (oz·in/ $\sqrt$ W)	0.024 (3.4)
<b>Mechanical Specifications</b>		
Motor Weight Without Tach	kg (lb)	0.189 (0.417)
Shaft Radial Load (Max) at Max Speed	N (lb)	20 (4.5)

**Table 3-19: ATX115SL/SLE Stepper Motor Specifications**

	Stepper Motor
Stall Torque	0.12 N·m
Rated Phase Current	1.3 A
Recommended Bus Voltage	24 V
Rotor Inertia	1.80E-06 kg·m <sup>2</sup>
Full Step Angle	1.8°
Phase Resistance	1.9 Ohm
Phase Inductance	1.70 mH
Maximum Speed	1800 rpm

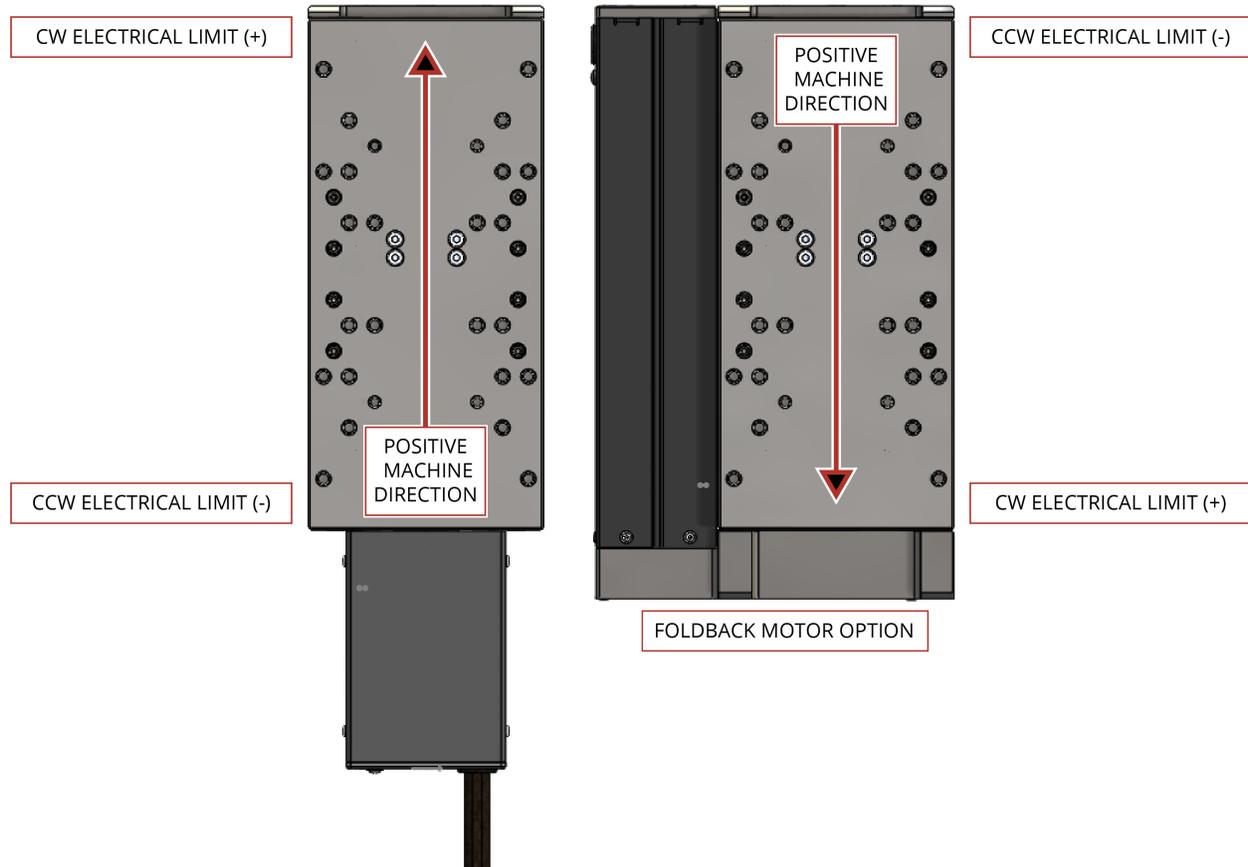
### 3.4. Limits, Marker, and Machine Direction

Aerotech stages have both a positive and negative **Machine Direction** and a positive and negative **Programming Direction**.

**Machine Direction:** The machine direction is defined by how the encoder and motor are mounted and the electrical wiring connections in the stage.

**Programming Direction:** Your system controller defines the programming direction of the stage and is application specific. A positive programmed move may or may not agree with the machine positive direction. Refer to your programming help documentation for more information.

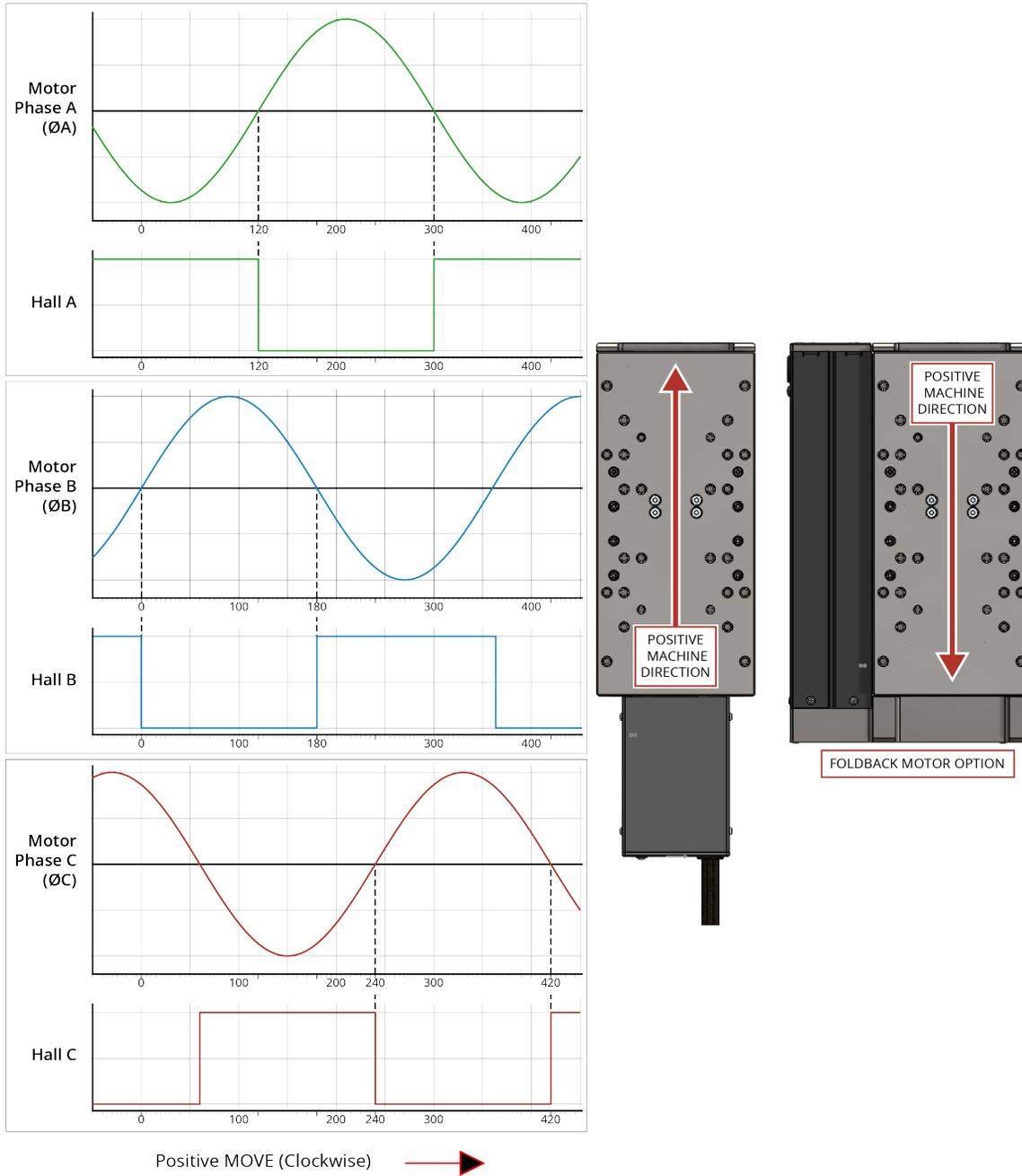
**Figure 3-7: Machine Direction**



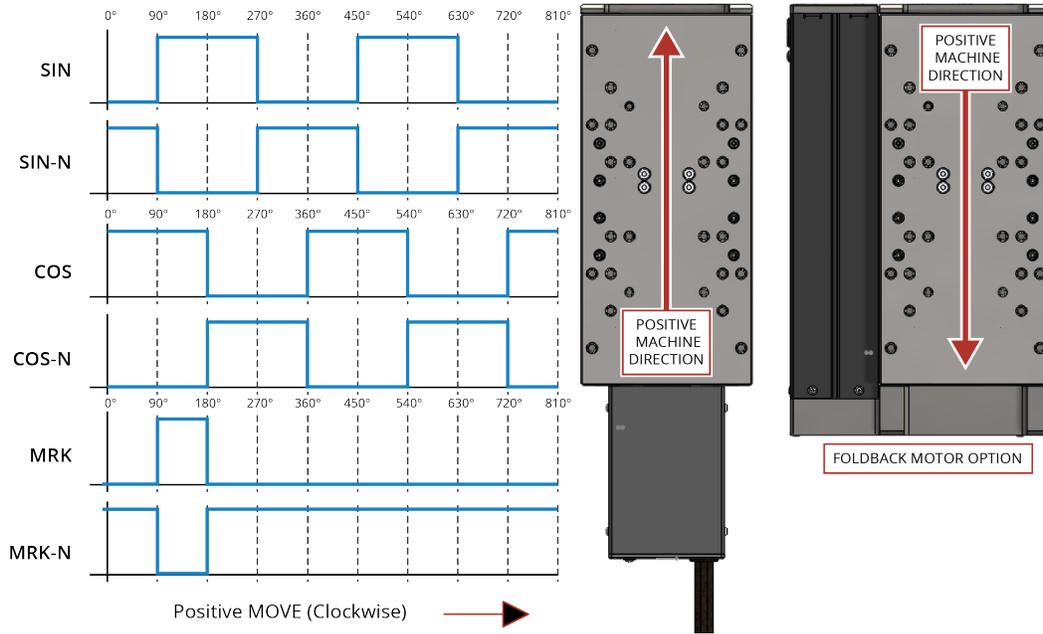
### 3.5. Motor and Feedback Phasing

Motor phase voltage is measured relative to the virtual wye common point.

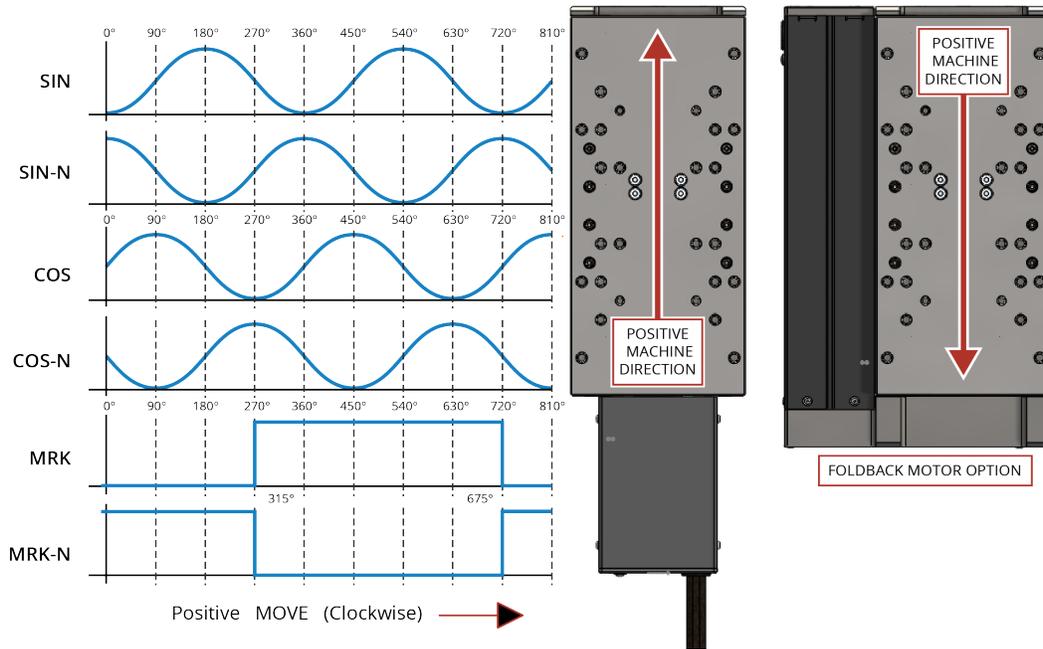
**Figure 3-8: Hall Phasing Diagram**



**Figure 3-9: Encoder Phasing Reference Diagram (Standard/Square Wave)**



**Figure 3-10: Digital Encoder Phasing Reference Diagram (Sine Wave)**



## Chapter 4: Maintenance



**IMPORTANT:** Read the [Safety Procedures and Warnings](#) (on [Page 8](#)) before you do maintenance to the stage.



**IMPORTANT:** Keep the bearing area free of foreign matter and moisture or the performance and life expectancy of the stage will be reduced.

### 4.1. Service and Inspection Schedule

Inspect the ATX115SL/SLE at least once per month. The need for a longer or shorter inspection interval will depend on the application and conditions, such as the duty cycle, speed, and environment.

Monthly inspections should include but not be limited to:

- Visually inspect the stage and cables.
- Re-tighten loose connectors.
- Replace or repair damaged cables.
- Clean the ATX115SL/SLE and any components and cables as needed.
- Repair any damage before operating the ATX115SL/SLE.
- Inspect and perform an operational check on all safeguards and protective devices.

## 4.2. Cleaning and Lubrication



**DANGER: Electrical Shock Hazard!** Before you do maintenance to the equipment, disconnect the electrical power.



**IMPORTANT:** Wear appropriate personal protective equipment (PPE) when you use cleaning solvents or lubricants.

In general, if the stage operates in a clean environment, it should be cleaned and lubricated annually or every 500 km (whichever comes first). For stages that are operated under conditions with excessive debris, the stage should be cleaned every six months. For high-speed applications (those near max speed at a duty cycle of 50%), more frequent maintenance with standard lubricants will be required.

When you clean and/or lubricate components of the ATX115SL/SLE series stage:

1. Use a clean, dry, soft, lint-free cloth for cleaning.
2. Before you use a cleaning solvent on any part of the stage, blow away small particles and dust with clean, dry, compressed air.
3. Take the opportunity during the lubrication procedure to inspect the motion guides or bearings for any damage or signs of wear.
4. In applications that have multiple stages bolted together to form multi-axis systems, the orthogonality can be lost if the stage tables of the support stages are loosened. Precision aligned stages should not be loosened or disassembled.
5. We recommend that you do not disassemble the stage beyond the instructions given in this manual. Proper assembly and calibration can only be done at the factory. Contact Aerotech for more information.

For stages equipped with foldback motors, you should check the belt tension when you clean or lubricate the stage. Refer to [Section 4.3](#).

### Cleaning

Use isopropyl alcohol if you must use a solvent to clean the stage. Harsher solvents, such as acetone, could damage the plastic and rubber seals on the ball screw and bearing trucks.



**WARNING: General Hazard Warning!** Make sure that all solvent has completely evaporated before you move the stage.

### Lubrication

You should only use Kluberplex BEM 34-132 as the standard lubricant for ATX115SL/SLE stages.

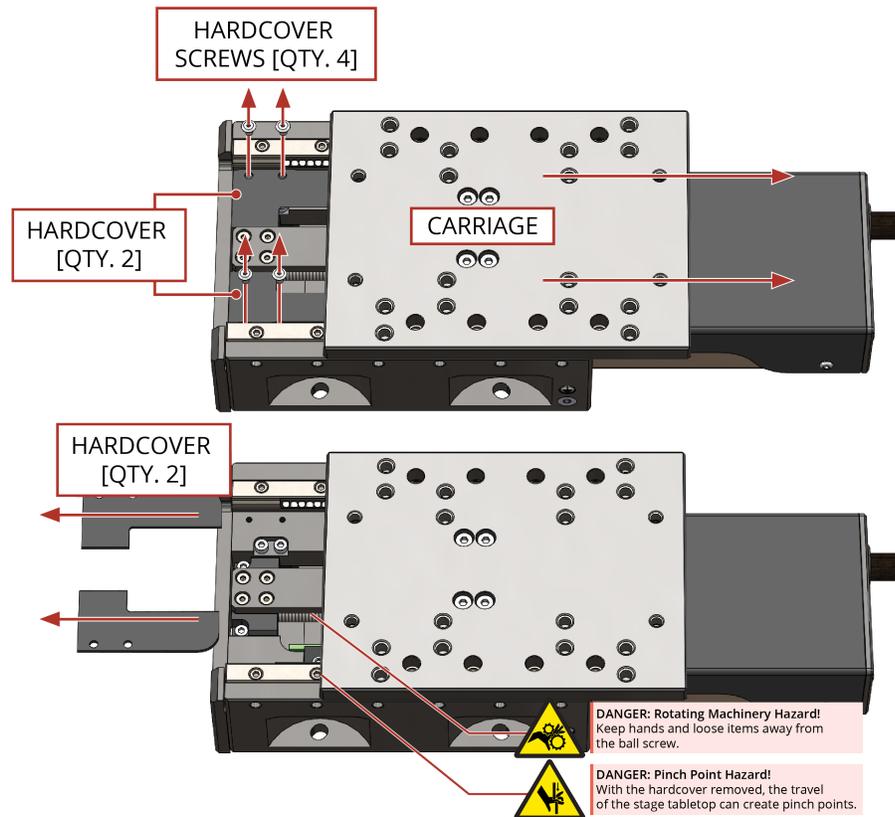
If the application process uses only a small portion of travel for most of the duty cycle, periodically drive the stage through full travel to redistribute the lubrication in the bearings.



**IMPORTANT:** During the lubrication procedure, inspect the bearings and ball screw for any damage or signs of wear.

1. Drive the stage to the end of travel closest to the motor.
  - Remove the four flat head screws
  - Slide the exposed hardcover out from under the carriage.

**Figure 4-1: Hardcover Removal (Left)**



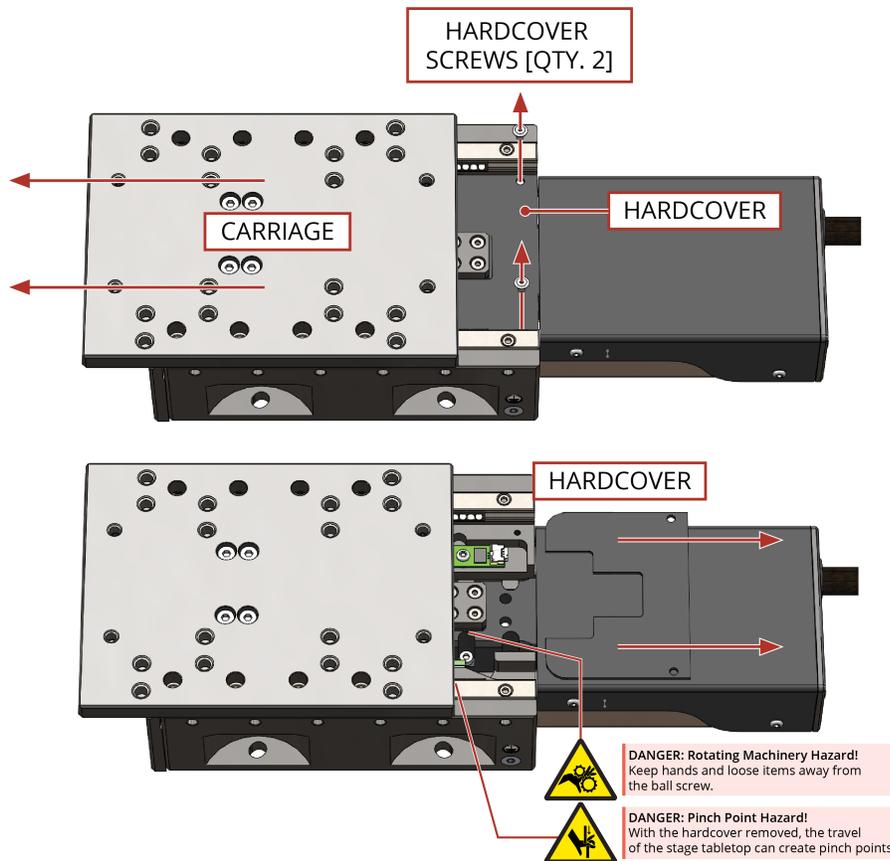
**DANGER: Mechanical Hazards!**

Use extreme caution when you operate the stage without the hardcover.



- **Rotating Machinery!** The ball screw can present a rotating machinery hazard.
- **Pinch Point!** The stage tabletop can present a pinch hazard.

2. Drive the stage to the other end of travel.
  - Remove the two flat head screws
  - Slide the exposed hardcover out from under the carriage.

**Figure 4-2: Hardcover Removal (Right)**

3. Remove any accumulated dust or debris from the inside of the assembly.
4. Remove any dirty or dried lubricant from the ball screw.
  - Use a clean, lint-free cloth with a side-to-side motion.
  - Use a swab soaked in Isopropyl Alcohol to remove stubborn debris.
5. Move the stage to the opposite end of travel. If the stage has an optional brake, the stage cannot be moved by hand.
  - If the stage has a brake: restore power to the stage, drive it to the desired position, then remove power
  - Redo Steps 3 and 4 for any areas covered by the previous table position.
6. Clean the end of the ball-screw nut and wiper with a clean, lint-free cloth or swab.
7. Clean the linear bearing guides with a clean, lint-free cloth or swab.
8. Apply a thin, continuous film of lubricant to the ball-screw threads and linear bearing guides. Aerotech recommends that you use a good quality, natural bristle artist's brush.
9. Move the stage to the opposite end of travel. If the stage has an optional brake, the stage cannot be moved by hand.
  - If the stage has a brake: restore power to the stage, drive it to the desired position, then remove power.
  - Redo Steps 6 through 8 for any areas covered by the previous table position.
10. Refasten the hardcovers. If the stage has an optional brake, the stage cannot be moved by hand.
  - If the stage has a brake: restore power to the stage, drive it to the desired position, then remove power.
  - Refasten the hardcover that was covered by the previous table position.
11. Restore power to the stage and drive the stage table back to its original position to redistribute lubricants.

### 4.3. Foldback Motor Belt Adjustment

This section applies to stages equipped with foldback motor options. On foldback stages, the motor torque is transferred to the ball screw via a timing belt. Belt tension is critical to stage performance and accuracy.

Check the belt tension when you clean or lubricate the stage. Deflection in the belt should be within  $\pm 10\%$  of 1.5 mm when applying a 5 N downward force directly between the pulleys. If the deflection exceeds this value, you will need to adjust the belt tension.

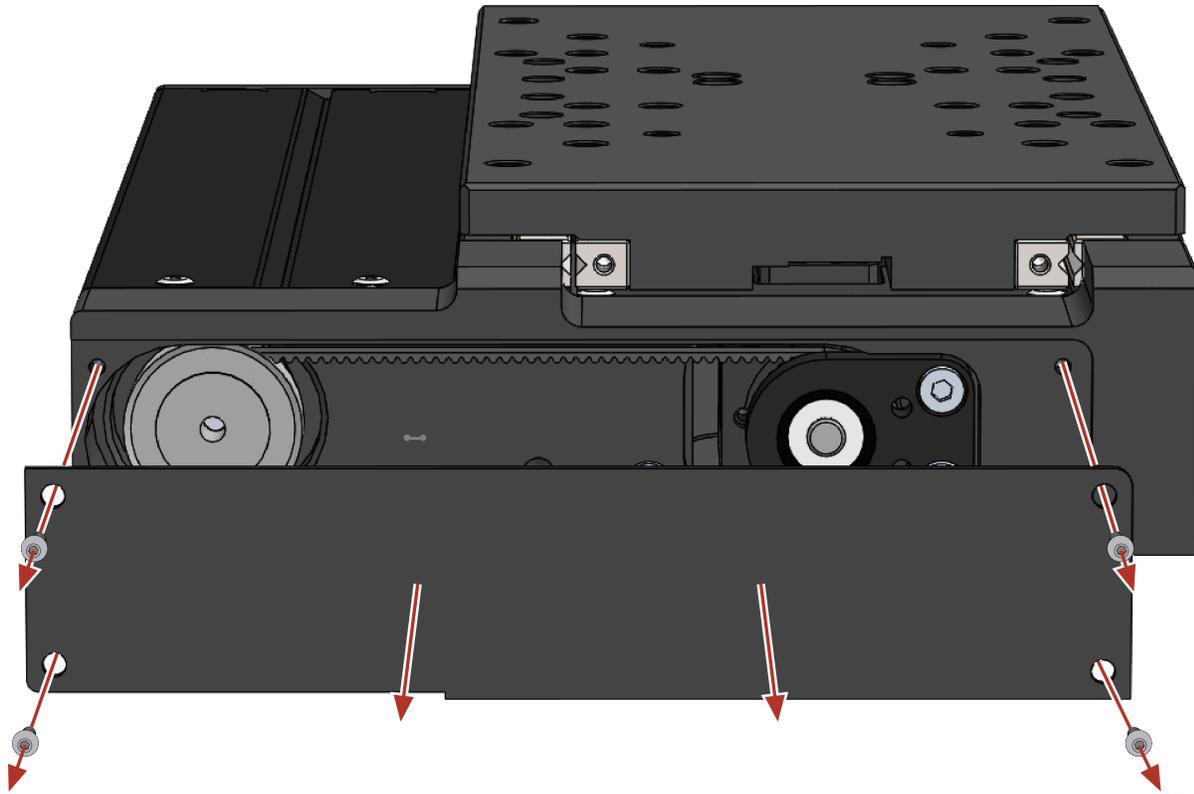


#### **DANGER: Rotating Machinery Hazard!**

Fingers and loose articles can get caught in the foldback belt or pulleys.

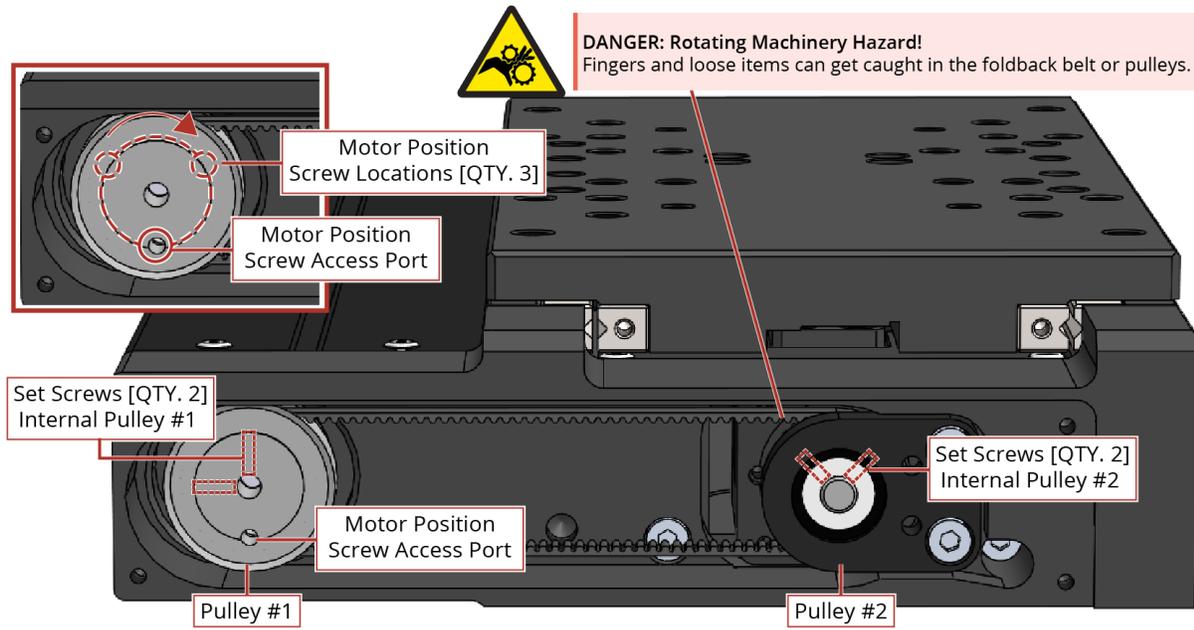
#### **Belt Tension Adjustment Procedure**

1. Remove power to the stage.
2. Remove the four mounting screws for the foldback cover and remove the foldback cover. Keep the cable guide and cable cover together ([Figure 4-3](#)).
3. Check that the pulleys are tight on their respective shafts ([Figure 4-4](#)).
  - Each pulley is held in position with two set screws.
  - Ensure that the set screws are tight and centered over the shaft flats.
4. Check the tension in the belt to determine if adjustment is necessary.
5. If adjustment is required, rotate the pulley connected to the motor (pulley #1 in [Figure 4-4](#)) in order to access the three screws holding the position of the motor. Loosen but do not remove these three screws.
6. Shift the motor and pulley assembly horizontally in order to increase or decrease the tension in the belt.
7. Re-tighten the three screws holding the motor position.
8. Measure the belt deflection again and repeat the previous steps until the belt tension adjustment is complete.
9. Replace the foldback cover and mounting screws.
10. Restore power to the stage and resume normal use.

**Figure 4-3: Foldback Motor Cover Removal**

**IMPORTANT:** If the stage has been calibrated (-PL2 option), note the orientation of the two pulleys with regard to each other or recalibration might be required.

Figure 4-4: Foldback Motor Part Callouts



## 4.4. Troubleshooting

Symptom	Possible Cause and Solution
Stage will not move	<p>Shipping brackets still installed. Remove the red anodized shipping brackets.</p> <p>Brake not released (if equipped with brake).</p> <p>In Limit condition. Check limits (refer to <a href="#">Chapter 3: Electrical Installation</a>) and refer to the Controller documentation for polarity and compatibility requirements (Example: voltage requirements).</p> <p>Controller trap or fault (refer to the Controller documentation).</p>
Stage moves uncontrollably	<p>Encoder (sine and cosine) signal connections (refer to <a href="#">Chapter 3: Electrical Installation</a> and Controller documentation).</p> <p>Motor Connections (refer to <a href="#">Chapter 3: Electrical Installation</a> and the Controller documentation).</p>
Stage oscillates or squeals	<p>Gains misadjusted (refer to the Controller documentation).</p> <p>Encoder signals (refer to the Controller documentation).</p>

## Appendix A: Warranty and Field Service

Aerotech, Inc. warrants its products to be free from harmful defects caused by faulty materials or poor workmanship for a minimum period of one year from date of shipment from Aerotech. Aerotech's liability is limited to replacing, repairing or issuing credit, at its option, for any products that are returned by the original purchaser during the warranty period. Aerotech makes no warranty that its products are fit for the use or purpose to which they may be put by the buyer, whether or not such use or purpose has been disclosed to Aerotech in specifications or drawings previously or subsequently provided, or whether or not Aerotech's products are specifically designed and/or manufactured for buyer's use or purpose. Aerotech's liability on any claim for loss or damage arising out of the sale, resale, or use of any of its products shall in no event exceed the selling price of the unit.

THE EXPRESS WARRANTY SET FORTH HEREIN IS IN LIEU OF AND EXCLUDES ALL OTHER WARRANTIES, EXPRESSED OR IMPLIED, BY OPERATION OF LAW OR OTHERWISE. IN NO EVENT SHALL AEROTECH BE LIABLE FOR CONSEQUENTIAL OR SPECIAL DAMAGES.

### Return Products Procedure

Claims for shipment damage (evident or concealed) must be filed with the carrier by the buyer. Aerotech must be notified within thirty (30) days of shipment of incorrect material. No product may be returned, whether in warranty or out of warranty, without first obtaining approval from Aerotech. No credit will be given nor repairs made for products returned without such approval. A "Return Materials Authorization (RMA)" number must accompany any returned product(s). The RMA number may be obtained by calling an Aerotech service center or by submitting the appropriate request available on our website ([www.aerotech.com](http://www.aerotech.com)). Products must be returned, prepaid, to an Aerotech service center (no C.O.D. or Collect Freight accepted). The status of any product returned later than thirty (30) days after the issuance of a return authorization number will be subject to review.

Visit [Global Technical Support Portal](#) for the location of your nearest Aerotech Service center.

### Returned Product Warranty Determination

After Aerotech's examination, warranty or out-of-warranty status will be determined. If upon Aerotech's examination a warranted defect exists, then the product(s) will be repaired at no charge and shipped, prepaid, back to the buyer. If the buyer desires an expedited method of return, the product(s) will be shipped collect. Warranty repairs do not extend the original warranty period.

**Fixed Fee Repairs** - Products having fixed-fee pricing will require a valid purchase order or credit card particulars before any service work can begin.

**All Other Repairs** - After Aerotech's evaluation, the buyer shall be notified of the repair cost. At such time the buyer must issue a valid purchase order to cover the cost of the repair and freight, or authorize the product(s) to be shipped back as is, at the buyer's expense. Failure to obtain a purchase order number or approval within thirty (30) days of notification will result in the product(s) being returned as is, at the buyer's expense.

Repair work is warranted for ninety (90) days from date of shipment. Replacement components are warranted for one year from date of shipment.

### Rush Service

At times, the buyer may desire to expedite a repair. Regardless of warranty or out-of-warranty status, the buyer must issue a valid purchase order to cover the added rush service cost. Rush service is subject to Aerotech's approval.

### On-site Warranty Repair

If an Aerotech product cannot be made functional by telephone assistance or by sending and having the customer install replacement parts, and cannot be returned to the Aerotech service center for repair, and if Aerotech determines the problem could be warranty-related, then the following policy applies:

Aerotech will provide an on-site Field Service Representative in a reasonable amount of time, provided that the customer issues a valid purchase order to Aerotech covering all transportation and subsistence costs. For warranty field repairs, the customer will not be charged for the cost of labor and material. If service is rendered at times other than normal work periods, then special rates apply.

If during the on-site repair it is determined the problem is not warranty related, then the terms and conditions stated in the following "On-Site Non-Warranty Repair" section apply.

### On-site Non-Warranty Repair

If any Aerotech product cannot be made functional by telephone assistance or purchased replacement parts, and cannot be returned to the Aerotech service center for repair, then the following field service policy applies:

Aerotech will provide an on-site Field Service Representative in a reasonable amount of time, provided that the customer issues a valid purchase order to Aerotech covering all transportation and subsistence costs and the prevailing labor cost, including travel time, necessary to complete the repair.

### Service Locations

<https://www.aerotech.com/contact-sales.aspx?mapState=showMap>

#### **USA, CANADA, MEXICO**

Aerotech, Inc.  
Global Headquarters

#### **CHINA**

Aerotech China  
Full-Service Subsidiary

#### **GERMANY**

Aerotech Germany  
Full-Service Subsidiary

#### **TAIWAN**

Aerotech Taiwan  
Full-Service Subsidiary

#### **UNITED KINGDOM**

Aerotech United Kingdom  
Full-Service Subsidiary

## Appendix B: Revision History

Revision	Description
2.00	<ul style="list-style-type: none"><li>• General updates</li><li>• Safety section updated</li></ul>
1.03	Added maximum speed for all motor options: <a href="#">Section 1.3</a> .
1.02	Updated dimension drawing
1.01	Updated dimension drawing
1.00	New Manual

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